# ON HARMONIC MEASURE FOR LÉVY PROCESSES 

BY

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#### Abstract

Let $\left\{X_{t}\right\}$ be a Lévy process in $\boldsymbol{R}^{d}, d \geqslant 2$, with infinite Lévy measure. If $\left\{X_{t}\right\}$ has no Gaussian component, then the process does not hit the boundary of Lipschitz domain $S \subset \boldsymbol{R}^{d}$ at the first exit time of $S$ under mild conditions on $\left\{X_{t}\right\}$. The conditions are met, e.g., if $\left\{X_{t}\right\}$ is rotation invariant.


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1. Introduction. The paper is concerned with the properties of the harmonic measure of Lévy process $\left\{X_{t}\right\}_{t \geqslant 0}$ in $\boldsymbol{R}^{d}$. Recall that for an open set $S \subset \boldsymbol{R}^{d}$ the harmonic measure $\omega_{S}^{x}$ corresponding to $\left\{X_{t}\right\}_{t \geqslant 0}$ is defined as $\omega_{S}^{x}(\cdot)=P^{x}\left(X_{\tau_{s}} \in \cdot\right)$, where $x \in \boldsymbol{R}^{d}$ and $\tau_{S}=\inf \left\{t>0: X_{t} \notin S\right\}$. For the Brownian motion in $\boldsymbol{R}^{d}$ the continuity of paths yields $\omega_{S}^{x}(\partial S)=1$ for every domain $S$ and all $x \in S$. However, in general, $\left\{X_{t}\right\}_{t \geqslant 0}$ has discontinuous paths and, depending on the process and the domain, it may happen that with probability one the process does not hit the boundary of $S$ when first leaving it. For example, for the rotation invariant stable Lévy process in $\boldsymbol{R}^{d}$ we have $\omega_{S}^{x}(\partial S)=0$, provided $S$ is a bounded domain with the outer cone property (see [2], Lemma 6). If $\omega_{S}^{x}(\partial S)=0$ for $x \in S$, then the harmonic measure may be completely described by means of the Green function and Lévy measure via a formula of Ikeda and Watanabe [3]. This motivates the search for general conditions on the Lévy process and the domain guaranteeing the discontinuous exit property: $\omega_{S}^{x}(\partial S)=0, x \in S$.

In the one-dimensional case this exit problem was completely solved in [5] in the case where $S$ is a half-line. The problem becomes much more difficult to handle in $\boldsymbol{R}^{d}$ for $d \geqslant 2$ because for some processes the discontinuous exit prop-

[^0]erty depends on global geometric properties of $\partial S$ (see [6] for the example). P. W. Millar gave a general solution of the exit problem in [6], but geometric conditions on $S$ imposed there are complicated and rather restrictive.

The primary purpose of the present paper is to use the methods of [6] to formulate simple conditions on the local geometry of $\partial S$ which yield the discontinuous exit property for a broad class of Lévy processes including rotation invariant processes with infinite Lévy measure and no Gaussian component. We have the following result (for the notation see the Preliminaries):

Theorem 1. Let $S \subset \mathbb{R}^{d}$ be a Lipschitz domain. Assume that $\left\{X_{t}\right\}_{t \geqslant 0}$ satisfies $\mathbf{H}$ and its resolvent is strong Feller. If

$$
\int_{V \cap B(0,1)} E^{0} \tau_{B(0,|y|)} v(d y)=\infty
$$

for every cone $V$ with vertex 0 , then

$$
P^{x}\left(X_{\tau_{S}} \in \partial S\right)=0 \quad \text { for every } x \in S .
$$

The hypotheses on $\left\{X_{t}\right\}_{t \geqslant 0}$ given in Theorem 1 are satisfied, e.g., by every rotation invariant process with the infinite Lévy measure and no Gaussian component. The same holds true for any transient stable process of type A having the scaling property under mild conditions on $v$ (see [6]).

For more general processes we relax the geometric condition on $S$ imposed in [6] to cover such domains as tori; see Theorem 2 below. We also point out that conditions of Millar on $S$, if imposed at every point of $\partial S$, characterize Lipschitz domains in $\boldsymbol{R}^{\boldsymbol{d}}$.
2. Preliminaries. For the rest of the paper, let $d \geqslant 2$. We denote by $\left\{X_{t}\right\}_{t \geqslant 0}$ the process with stationary independent increments in $\boldsymbol{R}^{\boldsymbol{d}}$ and the characteristic function

$$
E^{0} \exp \left\{i\left(u, X_{t}\right)\right\}=\exp \{-t \Phi(u)\}, \quad u \in \boldsymbol{R}^{d}, t \geqslant 0
$$

where

$$
\Phi(u)=i(a, u)+\frac{1}{2}(\sigma u, u)+\int_{\mathbf{R}^{d}}\left(1-e^{i(u, y)}+\frac{i(u, y)}{1+|y|^{2}}\right) v(d y)
$$

$v$ denotes the Lévy measure, $a \in \boldsymbol{R}^{d}$, and $\sigma$ is a positive semidefinite symmetric matrix. As usual, $E^{x}$ denotes the expectation with respect to the distribution $P^{x}$ of the process starting from $x \in \boldsymbol{R}^{d}$. We always assume that sample paths of $X_{t}$ are right-continuous and have left-hand limits a.s. The process is Markov with transition probabilities given by $P_{t}(x, A)=P^{x}\left(X_{t} \in A\right)=P^{0}\left(X_{t} \in A-x\right)$. It is well known that $\left\{X_{t}\right\}_{t \geqslant 0}$ is strong Markov with respect to the so-called "standard filtration", and quasi-left-continuous on [0, $\infty$ ] (see, e.g., [1]).

For $x \in \boldsymbol{R}^{d}$ and $r>0$, we let $B(x, r)=\left\{y \in \boldsymbol{R}^{d}:|x-y|<r\right\}$ and dist $(x, A)=$ $\inf \{|x-y| ; y \in A\}, \quad \operatorname{dist}(A, B)=\inf \{|x-y| ; x \in A, y \in B\}$ for $A, B \subset \boldsymbol{R}^{d}$. As
usual, $A^{c}$ is the complement of $A$. For $A \subset \boldsymbol{R}^{d}$ we define $T(A)=\inf \{t>0$; $\left.X_{t} \in A\right\}$, the first hitting time of $A$, and $\tau_{A}=T\left(A^{c}\right)$, the first exit time of $A$. For $r>0$ we put $\tau_{r}=\tau_{B(0, r)}$.

A cone in $\boldsymbol{R}^{d}$ with vertex at 0 is any set $V$ that can be constructed as follows: take a closed ball $B$ of radius $r>0$ whose center is at the distance $r_{0}>r$ from 0 ; then $V$ consists of all the points that lie on the rays passing from 0 through $B$. The axis of $V$ is the ray from 0 through the center of the ball, the vertex angle is $2 \sin ^{-1}\left(r / r_{0}\right)$. A cone with vertex at $x \in \boldsymbol{R}^{d}$ is a set of the form $x+V$, where $V$ is a cone with vertex at 0 . An open cone is the interior of a closed conę as just defined.

We say that a domain (a nonempty, connected and open set) $S$ has the outer cone property if there exist a constant $H>0$ and a cone $V$ such that for every $Q \in \partial S$ there is a cone $V_{Q}$ with vertex $Q$, isometric with $V$ and satisfying $V_{Q} \cap B(Q, H) \subset S^{c}$.

A domain $S \subset \boldsymbol{R}^{d}$ is called a Lipschitz domain if it is bounded and for each $Q$ in its boundary $\partial S$ there are: a Lipschitz function $\Gamma_{Q}: \boldsymbol{R}^{d-1} \rightarrow \boldsymbol{R}$, an orthonormal coordinate system $C S_{Q}$, and a number $R_{Q}>0$ such that if $z=\left(z_{1}, \ldots, z_{d}\right)$ in $C S_{Q}$ coordinates, then

$$
S \cap B\left(Q, R_{Q}\right)=\left\{z: z_{d}>\Gamma_{Q}\left(z_{1}, \ldots, z_{d-1}\right)\right\} \cap B\left(Q, R_{Q}\right) .
$$

We note that by compactness of $\partial S$, the radii $R_{Q}$ are not less than a constant $R_{0}>0$ (the localization radius of $S$ ), and the Lipschitz constants of the functions $\Gamma_{Q}$ are not greater than a constant $\lambda<\infty$ (the Lipschitz constant of $S$ ).

From the Lipschitz condition it easily follows that a Lipschitz domain has the outer cone property.

Definition 1. The process is said to satisfy hypothesis $H$ if for each $\alpha \in(0, \pi)$ there are $h(\alpha)>0$ and $r_{0}(\alpha)>0$ such that for all cones $V$ of vertex angle $\alpha$ and vertex at 0

$$
\begin{equation*}
E^{0} \int_{0}^{\tau_{r}} 1_{V}\left(X_{s}\right) d s \geqslant h(\alpha) E^{0} \tau_{r} \tag{1}
\end{equation*}
$$

for all $r \in\left(0, r_{0}(\alpha)\right)$.
Note that (1) is to hold for all cones with the same vertex angle, regardless of the direction of the cone. Any isotropic (rotation invariant) process has this property as well as processes with genuinely $d$-dimensional Gaussian component, stable processes of type $A$, and many others (see [6]).
3. Main results. Throughout this section, $S$ denotes a domain in $\boldsymbol{R}^{d}$. We record some auxiliary results due to Millar. The proofs can be found in [6]. In what follows we assume that if $\left\{X_{t}\right\}_{t} \geqslant 0$ has no Gaussian component, then $v\left(\boldsymbol{R}^{d}\right)=\infty$.

If $a \in(0,1)$, then there is a constant $K=K(a)>0$ such that

$$
\begin{equation*}
E^{0} \tau_{a r} \geqslant K(a) E^{0} \tau_{r} \tag{2}
\end{equation*}
$$

for all $r>0$.
Furthermore, if the resolvent of the process $\left\{X_{t}\right\}_{t \geqslant 0}$ is strong Feller, then the function $f(x)=P^{x}\left(X_{\tau_{S}} \in A\right)$ is continuous on $S$ for every Borel set $A \subset \boldsymbol{R}^{d}$

We call a point $y \in S$ possible if

$$
\begin{equation*}
P^{x}\left(T(B(y, \delta))<\tau_{S}\right)>0 \tag{3}
\end{equation*}
$$

for all $x_{0} \in S$ and all $\delta>0$. If $\left\{X_{t}\right\}_{t \geqslant 0}$ satisfy hypothesis $H$, then every point in $S$ is possible.

We also introduce a translation property, which is a weakening of the translation property defined in [6]. The modification enables us to handle a more general class of domains.

Definition 2. Let $V$ be a cone with vertex at 0 and $R>\varepsilon>0$. We say that $S$ has the translation property relative to $V, R, \varepsilon$ if
(a) $0 \in S$,
(b) $\partial S \cap V \cap B(0, R) \subset B(0, R-\varepsilon)$,
(c) for every cone $V^{\prime} \subset V, V^{\prime} \neq V$, with the same axis,

$$
\left[\partial S \cap V^{\prime} \cap B(0, R)\right]-y \subset S
$$

for all sufficiently small $y \in V$,
(d) there is a constant $c>0$ such that for all sufficiently small $y \in V$ the distance between $[\partial S \cap V \cap B(0, R)]-y$ and $\partial S \cap V$ is at least $c|y|$.

The following result is a generalization of Theorem 3.1 in [6].
Theorem 2. Let $S \subset \boldsymbol{R}^{d}$ be a domain with the outer cone property. Let $V$ be an open cone such that $S$ has the translation property relative to $V, R, \varepsilon$ for some $R>\varepsilon>0$. Assume that $\left\{X_{t}\right\}_{t} \geqslant 0$ satisfies hypothesis H and its resolvent is strong Feller. If $\int_{\boldsymbol{V} \cap \boldsymbol{B}(0,1)} E^{0} \tau_{|y|}^{v}(d y)=\infty$, then

$$
\begin{equation*}
P^{0}\left(X_{\tau s} \in \partial S \cap V \cap B(0, R)\right)=0 . \tag{4}
\end{equation*}
$$

Proof. We generally follow the lines of the proof of Theorem 3.1 in [6], so we only give a sketch of the proof.

Assume that (4) does not hold, i.e. there is $\delta>0$ such that

$$
P^{0}\left(X_{\tau s} \in \partial S \cap V \cap B(0, R)\right)=\delta
$$

Let $W=\left(\operatorname{int} S^{c}\right) \cap V \cap B(0, R)$. For $u, v \in \boldsymbol{R}^{d}$ we define $f(u, v)=\mathbb{1}_{S}(u) \mathbb{1}_{W}(v)$. We have

$$
P^{0}\left(X_{\tau s} \in W\right)=E^{0} \int_{0}^{\tau} \int_{R^{d}} f\left(X_{s}, X_{s}+y\right) v(d y) d s
$$

(see, e.g., [4] or [6]).

Let $V^{\prime}$ be an open cone contained in $V$ with the same axis and smaller vertex angle and such that $P^{0}\left(X_{\tau s} \in \partial S \cap V^{\prime} \cap B(0, R)\right) \geqslant \delta / 2$. For fixed $y \in V$ we define

$$
U_{y}=\left[\partial S \cap V^{\prime} \cap B(0, R)\right]-y, \quad D_{y}=S \cap(W-y)
$$

If $x \in \bar{U}_{y}=\left[\partial S \cap \bar{V}^{\prime} \cap B(0, R)\right]-y$, then from the outer cone property and the translation property relative to $V, R, \varepsilon$ we have $B(x, c|y|) \cap C_{x} \subset D_{y}$ for some cone $C_{x}$ with vertex $x$ and vertex angle $\beta \in(0, \pi)$ ( $\beta$ independent of $x$ ), provided $y$ is sufficiently small, say $|y|<\eta$ for some $\eta$. Using this fact, the strong Markov property and hypothesis:H we find that

$$
\begin{equation*}
E^{0} \int_{0}^{\tau_{s}} f\left(X_{s}, X_{s}+y\right) d s \geqslant h(\beta) E^{0} \tau_{c|y|} P^{0}\left(T\left(U_{y}\right)<\tau_{S}\right) \tag{5}
\end{equation*}
$$

For $n \geqslant 1$ we let

$$
\Delta_{n}=\{x \in S: \operatorname{dist}(x, \partial S)>1 / n\} \quad \text { and } \quad S_{n}=\left[S \cap V^{\prime} \cap B(0, R-\varepsilon)\right] \cup \Delta_{n}
$$

By quasi-left-continuity we have $P^{0}\left(X_{\tau_{s_{n}}} \in \partial S \cap V^{\prime} \cap B(0, R)\right) \geqslant \delta / 4$ if $n$ is sufficiently large. For such fixed $n$ we have $S_{n}-y \subset S$ provided $\eta<1 / n$, which we may and do assume.

The function $y \mapsto P^{y}\left(X_{\tau s_{n}} \in \partial S \cap V^{\prime} \cap B(0, R)\right)$ is continuous at 0 , so, by taking smaller $\eta$ we infer that, for $y \in V$ and $|y|<\eta$,

$$
\begin{align*}
P^{0}\left(T\left(U_{y}\right)<\tau_{s}\right) & \geqslant P^{0}\left(T\left(U_{y}\right)=\tau_{\left(S_{n}-y\right)}, T\left(U_{y}\right)<\infty\right)  \tag{6}\\
& \geqslant P^{y}\left(X_{\tau_{S_{n}}} \in \partial S \cap V^{\prime} \cap B(0, R)\right) \geqslant \delta / 8
\end{align*}
$$

because the resolvent of $\left\{X_{t}\right\}_{t \geqslant 0}$ is strong Feller.
Let $V_{\eta}=V \cap B(0, \eta)$. From (5), (6) and (2) we have

$$
\begin{aligned}
1 & \geqslant P^{0}\left(X_{\tau_{s}} \in W\right)=E^{0} \int_{0}^{\tau_{s}} \int_{\mathbf{R}^{d}} f\left(X_{s}, X_{s}+y\right) v(d y) d s \\
& \geqslant h(\beta) \frac{\delta}{8} \int_{V_{\eta}} E^{0} \tau_{c|y|} v(d y) \geqslant h(\beta) \frac{\delta}{8} K(c) \int_{V_{\eta}} E^{0} \tau_{|y|} v(d y)=\infty
\end{aligned}
$$

This is the required contradiction. The proof of (4) is complete.
We now digress on the consequences of the translation property, if imposed at every point of $\partial S$.

Definition 3. A domain $S \subset \boldsymbol{R}^{\boldsymbol{d}}$ is called a Millar domain if it is bounded, has the outer cone property, and for each $Q \in \partial S$ there are: an open cone $V_{x}$ with vertex $x \in S$ and numbers $R, \varepsilon$ such that $R>\varepsilon>0, Q \in V_{x} \cap B(x, R)$ and $S-x$ has the translation property relative to $V_{x}-x, R, \varepsilon$.

Lemma 1. A set is a Millar domain if and only if it is a Lipschitz domain.
Throughout the proof, for $z=\left(z_{1}, \ldots, z_{d-1}, z_{d}\right)$ we write $\tilde{z}=\left(z_{1}, \ldots, z_{d-1}\right)$ and $\|\tilde{z}\|^{2}=z_{1}^{2}+\ldots+z_{d-1}^{2}$.

Proof. Let $S$ be a Lipschitz domain with localization radius $R_{0}$ and Lipschitz constant $\lambda$. Choose $Q \in \partial S$. We may and do assume $Q=\left(0, \ldots, 0,-R_{0} / 2\right)$. Let $\Gamma_{Q}$ denote the Lipschitz function such that

$$
S \cap B\left(Q, R_{0}\right)=\left\{z: z_{d}>\Gamma(\tilde{z})\right\} \cap B\left(Q, R_{0}\right) .
$$

Set $V=\left\{z: z_{d}<0,\|\tilde{z}\|<\eta\left|z_{d}\right|\right\}$, where $\eta=\sqrt{\lambda^{2}+1}-\lambda$. The set $V$ is an open cone with vertex 0 . Let $R=R_{0} / \sqrt{\eta^{2}+1}+R_{0} / 2, \varepsilon=R_{0} / 2$.

We have $Q \in V \cap B(0, R)$. We will check that $S$ has the translation property relative to $V, R, \varepsilon$.
(a) $\dot{0} \in S$.
(b) Let $w \in \partial S \cap V \cap B(0, R)$. Then $w=t \theta$, where $t \in(0, R)$ and $\theta \in V$, $|\theta|=1$. We get

$$
|w-Q|^{2}=t^{2}+R_{0}^{2} / 4+t R_{0} \theta_{d}<t^{2}+R_{0}^{2} / 4-t R_{0} / \sqrt{\eta^{2}+1}<R_{0}^{2}
$$

so

$$
\begin{equation*}
\partial S \cap V \cap B(0, R) \subset B\left(Q, R_{0}\right), \tag{7}
\end{equation*}
$$

and hence $w_{d}=\Gamma_{Q}(\tilde{w})$. We have $\left|w_{d}+R_{0} / 2\right|=\left|\Gamma_{Q}(\tilde{w})-\Gamma_{Q}(0)\right| \leqslant \lambda\|\tilde{w}\|$ and $\|\tilde{w}\|<-\eta w_{d}$. From this we conclude that

$$
\|\tilde{w}\|<\frac{R_{0} / 2}{(1 / \eta)-\lambda}
$$

and $|w|^{2}=\|\tilde{w}\|^{2}+w_{d}^{2}<R_{0}^{2} /\left(1+\eta^{2}\right)=(R-\varepsilon)^{2}$, so

$$
\partial S \cap V \cap B(0, R) \subset B(0, R-\varepsilon) .
$$

(c) Fix $y \in V,|y|<R_{0} / 2$ and $w \in \partial S \cap V \cap B(0, R)$. The same method as for (7) shows that $\partial S \cap V \cap B(0, R-\varepsilon) \subset B\left(Q, R_{0} / 2\right)$, and this yields $w-y \in B\left(Q, R_{0}\right)$. We have $\left|\Gamma_{Q}(\tilde{w})-\Gamma_{Q}(\tilde{w}-\tilde{y})\right| \leqslant \lambda\|\tilde{y}\|$, so $\quad \Gamma_{Q}(\tilde{w}-\tilde{y})<w_{d}+\lambda \eta\left|y_{d}\right|<w_{d}-y_{d}$. Hence $w-y \in S$.
(d) Let $y \in V,|y|<\varepsilon / 2$ and $w \in \partial S \cap V \cap B(0, R)$ : We have $w-y \in B(0, R-\varepsilon / 2)$, so ${ }^{-}$

$$
\operatorname{dist}\left(w-y, \partial S \cap V \cap B^{c}(0, R)\right) \geqslant \varepsilon / 2>|y| .
$$

Let $\quad Z_{w}=\left\{z:\left|z_{d}-w_{d}\right| \leqslant \lambda\|\tilde{z}-\tilde{w}\|\right\}$. We have $\partial S \cap V \cap B(0, R) \subset Z_{w}$ and $w-y \notin Z_{w}$. Hence

$$
\operatorname{dist}(w-y, \partial S \cap V \cap B(0, R)) \geqslant \operatorname{dist}\left(w-y, \partial Z_{w}\right) .
$$

An easy computation shows that

$$
\operatorname{dist}\left(w-y, \partial Z_{w}\right)>\frac{1-\lambda \eta}{\sqrt{\left(\lambda^{2}+1\right)\left(\eta^{2}+1\right)}}|y|,
$$

so we may put

$$
c=\frac{1-\lambda \eta}{\sqrt{\left(\lambda^{2}+1\right)\left(\eta^{2}+1\right)}} \wedge 1
$$

The first part of the proof is complete.
Now, let $S$ denote a Millar domain.
Choose $Q \in \partial S$ and let a cone $V_{x}$ with vertex $x$ and $R, \varepsilon, R>\varepsilon>0$, be such that $Q \in V_{x} \cap B(x, R)$ and $S-x$ has the translation property relative to $V_{x}-x, R, \varepsilon$. We may and do assume that $x=0, Q=\left(0, \ldots, 0, q_{d}\right) ; q_{d}<0$ and $V_{x}=\left\{z: z_{d}<0,\|\tilde{z}\|<\eta_{x}\left|z_{d}\right|\right\}, \eta_{x}>0$.

Set $V=\left\{z: z_{d}<0,\|\tilde{z}\|<\eta\left|z_{d}\right|\right\}$, where $0<\eta<\eta_{x}$. Let $r>0$ be such that $[\partial S \cap V \cap B(0, R)]-y \subset S$ for each $y \in V_{x},|y|<r$. Set

$$
R_{1}=r / 2 \wedge \operatorname{dist}\left(Q, V^{c}\right) \wedge \operatorname{dist}\left(Q, B^{c}(0, R)\right)
$$

and for $w \in \partial S \cap B\left(Q, R_{1}\right)$ let

$$
M_{w}=(-V+w) \cap B\left(Q, R_{1}\right), \quad N_{w}=(V+w) \cap B\left(Q, R_{1}\right)
$$

Using the outer cone property and (c) from the definition of the translation property we get

$$
\begin{equation*}
M_{w} \subset S \quad \text { and } \quad N_{w} \subset \operatorname{int} S^{c} \tag{8}
\end{equation*}
$$

for each $w \in \partial S \cap B\left(Q, R_{1}\right)$. Set $R_{Q}=R_{1} \eta / \sqrt{\eta^{2}+1}$. For every $z \in B\left(Q, R_{Q}\right)$ there exists $z^{*} \in \boldsymbol{R}$ such that $\left(\tilde{z}, z^{*}\right) \in \partial S \cap B\left(Q, R_{1}\right)$. Moreover, from (8) it follows that there is only one such $z^{*}$. Therefore, we can define a function $\Gamma_{Q}(\tilde{z})=z^{*}, z \in B\left(Q, R_{Q}\right)$. Using (8) again we infer that $\Gamma_{Q}$ is the Lipschitz function with Lipschitz constant $\lambda=1 / \eta$ and

$$
S \cap B\left(Q, R_{Q}\right)=\left\{z: z_{d}>\Gamma_{Q}(\tilde{z})\right\} \cap B\left(Q, R_{Q}\right)
$$

Lemma 1 is a motivation to consider Lipschitz domains in the context of our exit problem. In a sense, Lipschitz domains are the most general domains for which Millar's methods may be used to prove the discontinuous exit property for typical Lévy processes.

Lemma 2. Let $A \subset \boldsymbol{R}^{d}$ be a Borel set. If $\left\{X_{t}\right\}_{t \geqslant 0}$ satisfies hypothesis $\mathbf{H}$, its resolvent is strong Feller, and there exists $x \in S$ such that $P^{x}\left(X_{\tau s} \in A\right)=0$, then $P^{z}\left(X_{\tau s} \in A\right)=0$ for all $z \in S$.

Proof. By the strong Markov property, for each $z \in S$ and $\delta>0$ we have

$$
\begin{aligned}
0=P^{x}\left(X_{\tau_{s}} \in A\right) & \geqslant P^{x}\left(X_{\tau_{s}} \in A ; T(\overline{B(z, \delta)})<\tau_{S}\right) \\
& =E^{x}\left(P^{X_{T(\overline{B(z, \delta)})}}\left(X_{\tau_{s}} \in A\right) ; T(\overline{B(z, \delta)})<\tau_{S}\right) .
\end{aligned}
$$

From (3) we get $P^{x}\left(T(\overline{B(z, \delta)})<\tau_{S}\right)>0$, so there exists $w \in \overline{B(z, \delta)}$ such that $P^{w}\left(X_{\tau_{s}} \in A\right)=0$. This yields that the set $\left\{w \in S: P^{w}\left(X_{\tau_{s}} \in A\right)=0\right\}$ is dense in $S$.

From continuity of the function $z \rightarrow P^{z}\left(X_{\tau s} \in A\right)$ we infer that $P^{z}\left(X_{\tau_{s}} \in A\right)=0$ for each $z \in S$.

Proof of Theorem 1. Let $Q \in \partial S$. By Lemma 1 there exists $x \in S$, an open cone $V_{x}$ with vertex $x$ and numbers $R, \varepsilon$ such that $Q \in V_{x} \cap B(x, R)$ and $S-x$ has the translation property relative to $V_{x}-x, R, \varepsilon$. We have

$$
\int_{\left(V_{x}-x\right) \cap B(0,1)} E^{0} \tau_{|y|} v(d y)=\infty .
$$

By Theorem 2 we get

$$
P^{0}\left(X_{\tau(S-x)} \in \partial(S-x) \cap\left(V_{x}-x\right) \cap B(0, R)\right)=0
$$

or

$$
P^{x}\left(X_{\tau s} \in \partial S \cap V_{x} \cap B(x, R)\right)=0
$$

Lemma 2 yields

$$
P^{z}\left(X_{\tau s} \in \partial S \cap V_{x} \cap B(x, R)\right)=0 \quad \text { for every } z \in S
$$

By the usual compactness argument, Theorem 1 holds true.
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