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DATA DRIVEN EFFICIENT SCORE TESTS FOR POISSONITY

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Abstract. New data driven score tests for testing goodness of fit of the Poisson distribution are proposed. They are direct applications of the general construction of data driven goodness-of-fit tests for composite hypotheses developed in Inglot et al. (1997). By a simulation study it is shown that these tests perform almost equally well as the best known solutions for standard alternatives and outperform them for more difficult alternatives.

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1. INTRODUCTION

The Poisson distribution is often used in modelling discrete distributions. So, testing goodness of fit of the Poisson family is an important problem in statistical inference. Beginning from Fisher's index of dispertion it has a large number of solutions and takes a constant interest in the literature. For a nice overview of existing tests we refer to Gürtler and Henze [3] and Best and Rayner [1]. Some further constructions have been proposed more recently, e.g., by Thas and Rayner [11], Meintanis and Nikitin [8], Frey [2] and Ledwina and Wyłupek [7].

In the present note we propose data driven efficient score tests for testing Poissonity which are a direct application of the general construction of data driven goodness-of-fit tests for composite hypotheses studied in Inglot et al. [5]. Our construction is valid for any family of discrete distributions concentrated on nonnegative integers. We focus on the most important case of testing for Poissonity to show that this construction leads to omnibus tests being able to compete with the best existing ones. Paying a little bit of sensitivity for simple alternatives, they cover a much wider class of alternatives with stable and high power. An additional advantage is that exact critical values for moderate sample sizes practically do not depend on the nuisance parameter and therefore can be determined in advance.

2. CONSTRUCTION OF THE TEST STATISTIC

Let X_1,\ldots,X_n be a sample from a discrete distribution P on the real line taking values in the set $\{0,1,2,\ldots\}$. Denote by P_λ the Poisson distribution with parameter $\lambda>0$, i.e. $P_\lambda(\{j\})=\pi_j(\lambda)=e^{-\lambda}\lambda_j/j!$ for $j=0,1,2,\ldots$ The problem is to test the composite hypothesis

$$H_0: P \in \{P_\lambda : \lambda > 0\}.$$

Let U_1, \ldots, U_n be independent random variables uniformly distributed over the unit interval [0,1] independent of X_i 's. Let us consider the randomized sample Y_1, \ldots, Y_n , where $Y_i = X_i + U_i$. Then Y_i 's have absolutely continuous distribution \overline{P} on the half line $[0,\infty)$ with a stepwise density constant on the intervals [j,j+1), $j \ge 0$. Now, consider a family \mathcal{P} of densities on $[0,\infty)$ defined by

(2.1)
$$\mathcal{P} = \left\{ f(y,\lambda) : f(y,\lambda) = \sum_{j=0}^{\infty} \pi_j(\lambda) \mathbf{1}_{[j,j+1)}(y), \ \lambda > 0 \right\},$$

where $\mathbf{1}_A(y)$ denotes the indicator of a set A. Since X_i 's take integer values, we can replace H_0 by the equivalent hypothesis

$$(2.2) H'_0: \overline{P} \in \mathcal{P}.$$

The cumulative distribution function of $f(y, \lambda)$ from \mathcal{P} takes the form

$$F(y,\lambda) = \sum_{r=0}^{j-1} \pi_r(\lambda) + (y-j)\pi_j(\lambda)$$
 for $y \in [j, j+1), j \ge 1$,

and $F(y,\lambda) = y \pi_0(\lambda)$ for $y \in [0,1)$. Hence, to test H'_0 we can simply apply results of Inglot et al. [5].

To this end, let $\psi_1(t), \psi_2(t), \ldots$ be an orthonormal system of bounded functions on [0,1] with $\int_0^1 \psi_j(t) dt = 0$ and such that $\partial \log f \big(F^{-1}(t,\lambda), \lambda \big) / \partial \lambda$ is linearly independent of $\psi_1(t), \psi_2(t), \ldots$ Let d(n) be a nondecreasing sequence of natural numbers. Consider the nested sequence $\mathcal{G}_k, 1 \leq k \leq d(n)$, of exponential families given by the densities

(2.3)
$$g_k(y, \vartheta, \lambda) = c_k(\vartheta) \exp \left\{ \sum_{j=1}^k \vartheta_j \psi_j (F(y, \lambda)) \right\} f(y, \lambda), \quad y \in [0, \infty),$$

where $\vartheta = (\vartheta_1, \dots, \vartheta_k)^T \in \mathbb{R}^k$ is a vector of parameters, v^T stands for the transposition of the vector v and $c_k(\vartheta)$ is the normalizing constant.

Fix $k, 1 \le k \le d(n)$. We reduce H_0' to $H_0'': \vartheta = 0$ in \mathcal{G}_k in the presence of the nuisance parameter λ . By standard calculations we get the score vector for H_0'' in \mathcal{G}_k of the form

$$\ell = (\ell_{\vartheta}^T, \ell_{\lambda})^T$$
 with $\ell_{\vartheta}(y) = \psi(F(y, \lambda)), \ \ell_{\lambda}(y) = \frac{\partial \log f(y, \lambda)}{\partial \lambda},$

where $\psi(t) = (\psi_1(t), \dots, \psi_k(t))^T$ is a vector of k first functions of the orthonormal system. Consequently, the effective score vector for H_0'' can be written as

(2.4)
$$\ell^*(y) = \psi(F(y,\lambda)) - I_{\vartheta\lambda} I_{\lambda\lambda}^{-1} \ell_{\lambda}(y),$$

where

$$I_{\lambda\lambda} = \int\limits_0^\infty \ell_\lambda^2(y) f(y,\lambda) dy = \sum\limits_{r=0}^\infty \left(rac{r}{\lambda} - 1
ight)^2 \pi_r(\lambda) = rac{1}{\lambda^2} \operatorname{Var} X = rac{1}{\lambda}$$

and

$$I_{\vartheta\lambda} = \int_{0}^{\infty} \psi(F(y,\lambda)) \ell_{\lambda}(y) f(y,\lambda) dy = \sum_{r=0}^{\infty} \int_{r}^{r+1} \psi(F(y,\lambda)) \left(\frac{r}{\lambda} - 1\right) f(y,\lambda) dy$$
$$= \frac{1}{\lambda} \sum_{r=1}^{\infty} r \int_{r}^{r+1} \psi(F(y,\lambda)) f(y,\lambda) dy = \frac{1}{\lambda} J.$$

Here the vector $J = J(\lambda)$ can be expressed as

$$J = \sum_{r=1}^{\infty} r \int_{F(r,\lambda)}^{F(r+1,\lambda)} \psi(t)dt = \sum_{r=1}^{\infty} r \left[\Psi(F(r+1,\lambda)) - \Psi(F(r,\lambda)) \right]$$
$$= -\sum_{r=0}^{\infty} \Psi(\pi_0(\lambda) + \dots + \pi_r(\lambda)),$$

where $\Psi(t) = \left(\Psi_1(t), \dots, \Psi_k(t)\right)^T$ is a vector of the functions

$$\Psi_j(t) = \int_0^t \psi_j(u) du, \quad t \in [0, 1].$$

The covariance matrix of the effective score vector has the usual form

$$I^* = I - I_{\vartheta \lambda} I_{\lambda \lambda}^{-1} I_{\vartheta \lambda}^T = I - \frac{1}{\lambda} J J^T,$$

where I denotes the identity matrix. Its inverse can be written as (cf. formula (3.2) in Inglot et al. [5])

$$(I^*)^{-1} = I + I_{\vartheta\lambda}(I_{\lambda\lambda} - I_{\vartheta\lambda}^T I_{\vartheta\lambda})^{-1} I_{\vartheta\lambda}^T = I + \frac{1}{\lambda - J^T J} J J^T.$$

In consequence, the effective score statistic for testing H_0'' in \mathcal{G}_k takes the form

$$N_k = \left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \ell^*(Y_i)\right)^T (I^*)^{-1} \left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \ell^*(Y_i)\right).$$

Since the natural estimator of the parameter λ is the sample mean $\widehat{\lambda} = \overline{X}$ which is the maximum likelihood estimator in the family \mathcal{P} , the estimated effective score vector has a simpler form, i.e. $\widehat{\ell}^*(y) = \psi(F(y,\widehat{\lambda}))$ (cf. (3.5) in [5]).

Finally, the test statistic for H_0'' in \mathcal{G}_k takes the form

(2.5)
$$\widehat{N}_k = \left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \psi(F(Y_i, \widehat{\lambda}))\right)^T \widehat{(I^*)^{-1}} \left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \psi(F(Y_i, \widehat{\lambda}))\right),$$

where

$$\widehat{(I^*)^{-1}} = I + \frac{1}{\widehat{\lambda} - \widehat{J}^T \widehat{J}} \widehat{J} \widehat{J}^T$$

and $\widehat{J} = -\sum_{r=0}^{\infty} \Psi \big(\pi_0(\widehat{\lambda}) + \ldots + \pi_r(\widehat{\lambda}) \big)$. Easy calculations show that regularity conditions (R1)–(R4) in [5] for $\mathcal P$ are satisfied. So, when ψ_j 's are twice differentiable and

(2.7)
$$\sup_{t \in [0,1]} |\psi_j(t)| \leqslant cj^m, \quad \sup_{t \in [0,1]} (|\psi_j'(t)| + |\psi_j''(t)|) \leqslant cj^{m+2}, \quad j \geqslant 1,$$

for some positive c and nonnegative m, it follows from Theorem 3.1 in [5] that under H_0'' , \hat{N}_k converges in distribution to the chi-square distribution with k degrees of freedom.

It is well known that the choice of k among $1,\ldots,d(n)$ is crucial to the performance of a test based on the score statistic \widehat{N}_k . Therefore, we propose a data driven choice of k using a Schwarz type selection rule (cf., e.g., Inglot et al. [5], Schwarz [10])

(2.8)
$$S = \min\{1 \le k \le d(n) : \widehat{N}_k - k \log n = \max_{1 \le j \le d(n)} (\widehat{N}_j - j \log n)\}.$$

Taking into account promising results in Inglot and Janic [4], we consider also another, less conservative, selection rule denoted by L. Choose two natural numbers (not depending on n): a small one $1 \le D < d(n)$ and a big one K, K > D, and set $K(n) = \min (K, d(n))$. Moreover, let δ_n be a small positive number. Define the thresholds $c_{jn}, j = 1, \ldots, D$, to be the solutions of the equations

$$1 - \Phi(c_{jn}) = \frac{1}{2} \left(\delta_n D^{-1} \begin{pmatrix} K(n) \\ j \end{pmatrix}^{-1} \right)^{1/j},$$

where Φ denotes the standard normal distribution function. Next, consider the standardized random vector $\mathcal{L} = \left(\widehat{(I^*)^{-1}}\right)^{1/2} \left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \psi \left(F(Y_i, \widehat{\lambda})\right)\right)$ with K(n) components, where $\widehat{(I^*)^{-1}}$ is given by (2.6) with k = K(n) while

$$\widehat{\left((\widehat{I^*})^{-1}\right)^{1/2}} = I + \frac{1}{\widehat{\lambda} - \widehat{J}^T \widehat{J} + \sqrt{\widehat{\lambda}(\widehat{\lambda} - \widehat{J}^T \widehat{J})}} \widehat{J} \widehat{J}^T.$$

Order the squares of its components from the smallest to the largest, obtaining $\mathcal{L}^2_{(1)}, \ldots, \mathcal{L}^2_{(K(n))}$, and consider the event

$$E_n = \{\mathcal{L}^2_{(K(n))} \geqslant c_{1n}^2\} \cup \ldots \cup \{\mathcal{L}^2_{(K(n)-D+1)} \geqslant c_{Dn}^2\}.$$

Then define the data dependent penalty

$$\rho(j,n) = j(\log n \cdot \mathbf{1}_{E_n^c} + 2 \cdot \mathbf{1}_{E_n}),$$

where $\mathbf{1}_{E_n}$ denotes the indicator of the event E_n and E_n^c is the complement of E_n , and define the corresponding selection rule L as

(2.9)
$$L = \min \{1 \le k \le d(n) : \widehat{N}_k - \rho(k, n) = \max_{1 \le j \le d(n)} (\widehat{N}_j - \rho(j, n)) \}.$$

By the definition, for $n \ge e^2$ we have $\rho(j,n) \le j \log n$ a.s. Consequently, $L \ge S$ a.s. and $\widehat{N}_L \ge \widehat{N}_S$ a.s.

Note that parameters D, K, δ_n were used only to define penalty $\rho(j, n)$ for L. In particular, introducing an upper bound K means that a choice of penalty for L is based on a limited number of empirical Fourier coefficients with respect to the system (ψ_j) .

By using all the above considerations, \widehat{N}_S and $\widehat{N}_L = \widehat{N}_L(D, K, \delta_n)$, where \widehat{N}_k is given by (2.5), can be applied as test statistics of upper-tailed tests for testing H'_0 (or equivalently H_0).

The asymptotic behavior of \widehat{N}_S and \widehat{N}_L is established in the following theorem.

THEOREM 2.1. Suppose $\psi_1(t), \psi_2(t), \ldots$ is an orthonormal system satisfying (2.7) and the maximal dimension d(n) of \mathcal{G}_k in (2.3) satisfies the condition $d(n) = o((n/\log n)^{1/(2m+4)})$. Then

$$\widehat{N}_S \stackrel{\mathcal{D}}{\to} \chi_1^2 \ under \ H_0,$$

where χ_k^2 denotes a random variable with chi-square distribution with k degrees of freedom.

If, in addition, $\delta_n \to 0$, then $L - S \to 0$ in probability with respect to any null distribution, and consequently

$$\widehat{N}_L \stackrel{\mathcal{D}}{\to} \chi_1^2 \text{ under } H_0.$$

Since the assumption on d(n) in Theorem 2.1 implies (D1)–(D3) in Inglot et al. [5], the assertion (2.10) follows from Theorem 4.1 in [5]. The assertion $L - S \to 0$ in probability under H_0 is an easy and straightforward consequence of the central limit theorem for the random vector \mathcal{L} due to the boundedness of K(n). We omit details.

From Theorems 2.6, 4.2 and 4.3 in [5] we immediately obtain a consistency result for the tests based on \widehat{N}_S and \widehat{N}_L .

THEOREM 2.2. Let $d(n) \to \infty$ and the conditions of Theorem 2.1 be satisfied. Then for any alternative discrete distribution P concentrated on nonnegative integers with probability mass function p_r , $r \ge 0$, and the expected value $\lambda > 0$ such that for some $j \ge 1$

(2.12)
$$\sum_{r=0}^{\infty} p_r \int_{r}^{r+1} \psi_j \big(F(y, \lambda) \big) dy \neq 0$$

we have $\widehat{N}_S \xrightarrow{P} \infty$ and $\widehat{N}_L \xrightarrow{P} \infty$. Consequently, the tests based on \widehat{N}_S and \widehat{N}_L are consistent against any P satisfying (2.12).

REMARK 2.1. When ψ_1, ψ_2, \ldots form a complete orthonormal system of bounded functions, then the assumption (2.12) is a weak one and is satisfied for a large class of alternatives. For example, if $p_r \leqslant C\pi_r(\lambda)$ for all $r \geqslant 0$ and some positive constant C, where $\lambda = \sum_{r=1}^{\infty} rp_r$, then (2.12) holds. In particular, (2.12) is satisfied for any distribution with finite support or with $p_r = \pi_r(\lambda)$ except finitely many r.

Now, we discuss two key choices needed for an implementation tests based on \widetilde{N}_S and \widetilde{N}_L in Section 3.

Firstly, we discuss a choice of an orthonormal system (ψ_i) . The most popular is the Legendre system on [0,1], we shall denote by (b_i) . It satisfies (2.7) with m=1/2. For our particular family \mathcal{P} of discontinuous densities this is rather not an optimal choice. In spite of this we do apply it in our implementation. However, for P_{λ} with small λ , high variation of b_j 's near zero has nothing to do with large values of the first few probabilities of P_{λ} and results in a less sensitive test. To overcome simply this problem we define another orthonormal system (h_i) with $h_j(t) = b_{2j}((1+t)/2)$. The functions h_j are smooth on the left end of [0, 1] with high variation only on the right end of the unit interval. So, we shall use the system (h_i) for small λ , say for $\lambda \leq \lambda_0$, and the system (b_i) otherwise. Since b_1 and h_1 are strongly correlated with $\ell_{\lambda}(F^{-1}(t,\lambda),\lambda)$, we remove them from the system. Data driven tests usually attain the highest power for alternatives for which the second empirical Fourier coefficient (under an actually applied orthonormal system) is the largest one. For most typical alternatives to the Poisson family the largest Fourier coefficient corresponds to b_2 or h_2 . So, we order the both systems as follows: $b_3, b_2, b_4, b_5, \ldots$ and $b_3, b_2, b_4, b_5, \ldots$ Since λ is unknown, we shall use the estimator λ to decide which orthonormal system will be applied in the test statistic. In effect, we define the orthonormal system (ψ_i) as follows:

$$\begin{array}{lll} (2.13) & & & & \\ \psi_1(t)=h_3(t) \text{ if } \widehat{\lambda}\leqslant \lambda_0 & \text{ or } & \psi_1(t)=b_3(t) \text{ otherwise,} \\ & & & & \\ \psi_2(t)=h_2(t) \text{ if } \widehat{\lambda}\leqslant \lambda_0 & \text{ or } & \psi_2(t)=b_2(t) \text{ otherwise,} \\ & & & & \\ \psi_j(t)=h_{j+1}(t) \text{ if } \widehat{\lambda}\leqslant \lambda_0 & \text{ or } & \psi_j(t)=b_{j+1}(t) \text{ otherwise,} \end{array}$$

The test statistics \widehat{N}_S and \widehat{N}_L for such a switched over orthonormal system will be denoted by M_S and M_L , respectively. The tests based on these statistics are examples of data driven score tests with an orthonormal system depending on the data. Since the system (h_j) satisfies (2.7), Theorem 2.1 applies to (h_j) and to M_S and M_L as well. Also, after some small obvious reformulation, the statement of Theorem 2.2 remains valid for both M_S and M_L .

Secondly, let us discuss a choice of the maximal dimension d(n). The assumption of Theorem 2.1 as well as properties of our particular family \mathcal{P} of the Poisson distributions suggest to take a slowly increasing sequence $d(n) = \lfloor cn^r \rfloor$ with r < 1/5. When M_L is applied, the relation $c \ge D$ seems to be reasonable. Moreover, for moderate sample sizes d(n) < K (if K is not too small). Therefore, a choice of K has practically no influence on the selection rule L for moderate sample sizes. But, it allows for simplifying assumptions in Theorems 2.1 and 2.2.

The above specifications can be thought only as reasonable recommendations. For example, at a cost of some loss in power for alternatives with small expectations λ , one can consider simply tests based on \widehat{N}_S or \widehat{N}_L for the Legendre system (b_i) without switching the orthonormal system.

We end this section by a brief comment how a randomization of a given sample $\underline{X}=(X_1,\ldots,X_n)$ by noise values U_1,\ldots,U_n may influence the acceptance or rejection decision of the null hypothesis. One may expect that when the sample \underline{X} , at hand, is "typical", then the randomization will change the decision rarely. We have roughly verified this statement by some empirical study taking n=50 and $\alpha=0.05$. We have observed that the distribution of conditional power $\beta(n|\underline{X})$ for our tests is strongly polarized, i.e. strongly concentrated near 0 and 1. Under null distributions, $\beta(n|\underline{X})$ belong to the interval [0,0.1] for ca. 85–95% of samples \underline{X} while $\beta(n|\underline{X})$ do not exceed the nominal significance level 0.05 for ca. 75–85% of samples \underline{X} . Under alternatives, $\beta(n|\underline{X})$ lie outside the interval (0.1,0.9) for ca. 70% of samples \underline{X} and divide between [0,0.1] and [0.9,1] approximately proportionally to the (unconditional) power $\beta(n)$ attained by the test.

3. SIMULATION STUDY

The aim of this section is to study how our new tests based on M_S and M_L , described in Section 2, perform empirically in comparison with some known tests for Poissonity which proved to be powerful, particularly with the test $\widetilde{T} = \widetilde{T}_n$ of Klar [6].

We restrict our attention to a typical sample size n=50 and standard significance level $\alpha=0.05$. We take the orthonormal system (ψ_j) defined in (2.13) and the maximal dimension of the exponential model d(n)=5 for n=50 which roughly corresponds to the formula $d(n)=\lfloor 3n^{1/7}\rfloor$. For the selection rule L we took D=3, K=20 and $\delta_n=0.05$. An analysis of values $\pi_r(\lambda)$ for small r and different λ suggests to choose λ_0 nearby 2. We took $\lambda_0=1.8$.

The behavior of all compared tests for other sample sizes is similar to that for n = 50, so we do not report it here.

3.1. Critical values of M_S and M_L . Nowadays it is a strong evidence that, for data driven tests, the convergence of M_S and M_L to the limiting null chi-square distribution with one degree of freedom is slow. So, we have determined the critical values empirically. The results are shown in Table 1. They practically do not depend on the nuisance parameter λ . This is not surprising since our tests are asymptotically distribution free. The results from Table 1 fully justify that average simulated critical values 5.910 for M_S and 7.092 for M_L may be used as fixed critical values for the sample size n=50.

Table 1. Empirical critical values of M_S and M_L for several values of λ , n=50, $\alpha=0.05$, 30,000 MC.

	0.2		1					Average
M_S	5.874	5.877	5.892	5.964	5.818	5.907	6.036	5.910
M_L	7.095	6.994	6.997	7.258	6.878	7.259	7.165	7.092

Under the same d(n), D, K, δ_n , λ_0 and α , average critical values for the sample size n=25 equal 6.842 for M_S and 7.592 for M_L ; and similarly 5.416 and 6.789 for n=100; 4.967 and 6.550 for n=200; 4.288 and 6.342 for n=500; respectively.

3.2. Power comparisons. For easier comparisons with the results available in the literature, we start our study with the list of 20 alternatives considered in the recent paper by Ledwina and Wyłupek [7]. In most cases we apply the notation from that paper or from Gürtler and Henze [3]. For completeness, we present description of all alternatives in the Appendix. We choose three tests for comparison which proved to be powerful: the test \widetilde{T} (proposed by Klar [6] and in his notation), the test I (proposed by Klar [6] in the notation of Gürtler and Henze [3]) and the test V^* of Nakamura and Pérez-Abreu [9]. Detailed description of these tests is also provided in the Appendix. For M_S and M_L we take critical values determined in Section 3.1. The results are shown in Table 2.

In the upper part of Table 2 we collect 'smooth' alternatives, i.e. those for which only one or two first Fourier coefficients (with respect to (ψ_j) given in (2.13)) are significant, and in the lower part we put alternatives with wider spectrum. To some extent, 'smoothness' is related to a number and positions of changes of sign for differences $p_r - \pi_r(\lambda)$, where $\lambda = \sum_{r\geqslant 1} rp_r$ is the expectation of an alternative. Since M_L has been designed to be more sensitive for 'less smooth' alternatives, it can be seen that in the upper part of Table 2 M_S is better than M_L while in the lower part an opposite relation occurs. Powers of \widetilde{T} , I and V^* have been taken from Ledwina and Wyłupek [7].

The test I is unstable. For some cases it attains extremely high power (cf. b(10,0.5)) but for some others, poor power (e.g. U(5;15) or TG(0.45)). The test \widetilde{T}

performs more stable than V^* and outperforms it in average. Data driven tests M_S and particularly M_L are very stable and both perform equally well. For alternatives presented in Table 2, \widetilde{T} outperforms M_S and M_L ca. 7% in average.

TABLE 2. Powers (in %) of $M_S, M_L, \widetilde{T}, I$ and V^* for twenty alternatives, $n = 50, \alpha = 0.05, 10,000$ MC.

Alternative	M_S	M_L	\widetilde{T}	I	V^*	λ
U(0;1)	79	76	98	99	94	0.5
U(0;2)	57	57	64	68	73	1
b(10, 0.5)	75	68	81	88	60	5
b(20, 0.35)	33	27	37	46	19	7
nb(2,2/3)	28	28	42	45	48	1
$P\delta(0.9,3)$	38	38	33	45	48	2.7
$P\delta(0.7, 1.5)$	45	42	59	59	52	1.05
GP(3, -0.24)	30	24	38	46	19	2.42
$GP\delta(4.59, -0.33, 0.025)$	41	35	49	53	33	3.36
GH(0.5, 0.25)	42	41	57	58	53	1
PSS(1, 0.75)	56	55	77	78	74	0.75
TG(0.45)	83	85	86	47	73	2.22
Average	50.6	48.0	60.1	61.0	53.8	
U(0;4)	44	51	60	16	73	2
U(5;15)	35	47	39	7	53	10
PP(0.1, 1.1, 6.9)	55	60	56	54	55	6.3
PP(0.1, 1.1, 6.1)	46	50	45	44	43	5.6
$GP\delta(4.59, -0.33, 0.127)$	63	64	55	21	56	3
PBM(0.55, 10, 0.97)	95	96	97	94	93	9.7
BB(5, 1.6, 0.67)	94	95	99	96	99	3.5
BB(5, 1, 0.67)	83	88	93	48	96	3
Average	64.4	68.9	68.0	47.5	71.0	
Total average	56.1	56.4	63.3	55.6	60.7	

The alternatives considered in Table 2 are well-known families of discrete distributions and not necessarily represent typical departures from the Poisson family. More realistically one may expect small changes of several probabilities π_j of P_λ . To see how our new tests are able to detect such contaminated Poisson distributions, we introduce three additional families of alternatives.

The first alternative is a modification of $P_{0.5}$ and preserves its expectation 0.5. We replace four first probabilities $\pi_0(0.5), \pi_1(0.5), \pi_2(0.5)$ and $\pi_3(0.5)$ by $\pi_0(0.5) - u + a + 2b, \ \pi_1(0.5) + v - 2a - 3b, \ a$ and b, respectively, with $u = \pi_2(0.5) + 2\pi_3(0.5)$ and $v = 2u - \pi_3(0.5)$, and keep the remaining probabilities unchanged. Parameters a, b are nonnegative with 2a + 3b not exceeding $\pi_1(0.5) + v$. We shall denote this alternative by $A_4^{0.5}(a, b)$.

The second alternative modifies P_{λ} with any λ and preserves its expectation λ . We replace four probabilities $\pi_j(\lambda), \pi_{j+1}(\lambda), \pi_{j+2}(\lambda)$ and $\pi_{j+3}(\lambda)$ by $\pi_j(\lambda) + c, \pi_{j+1}(\lambda) - c, \pi_{j+2}(\lambda) - c, \pi_{j+3}(\lambda) + c$, respectively, and keep the remaining probabilities unchanged. The parameter j is a nonnegative integer while c can take positive or negative values in such a way that all four obtained numbers are nonnegative. We shall denote this alternative by $A_4(\lambda, j, c)$.

The third alternative modifies P_{λ} with any λ and also preserves its expectation λ . We replace eight probabilities $\pi_{j}(\lambda),\ldots,\pi_{j+7}(\lambda)$ by $\pi_{j}(\lambda)+a+b+c,$ $\pi_{j+1}(\lambda)-a-b-c,$ $\pi_{j+2}(\lambda)-a,$ $\pi_{j+3}(\lambda)+a,$ $\pi_{j+4}(\lambda)-b,$ $\pi_{j+5}(\lambda)+b,$ $\pi_{j+6}(\lambda)-c,$ $\pi_{j+7}(\lambda)+c,$ respectively, and keep the remaining probabilities unchanged. The parameter j is a nonnegative integer while a,b,c are such that all resulting numbers are nonnegative. We shall denote this alternative by $A_{8}(\lambda,j,a,b,c)$.

In Table 3 we show, by typical examples of new alternatives, empirical powers of M_S and M_L compared with \widetilde{T} , the leader in Table 2. It can be observed that for more difficult alternatives the new test M_L performs essentially better than \widetilde{T} .

Table 3. Powers of M_S, M_L and \widetilde{T} for seven selected alternatives. $n=50, \alpha=0.05, 10,000$ MC for M_S and M_L , and 5000 MC for \widetilde{T} .

Alternative	M_S	M_L	\widetilde{T}
$A_4^{0.5}(0.05, 0.05)$	22	24	33
$A_4^{0.5}(0, 0.07)$	33	45	39
$A_4(5,1,0.08)$	49	62	28
$A_4(7,7,0.10)$	27	45	27
$A_8(3,0,0.04,-0.09,0.05)$	33	46	38
$A_8(5,3,0.10,-0.05,0.036)$	54	71	49
$A_8(9, 9, 0.097, -0.02, 0.019)$	18	30	23
Average	33.7	47.1	33.9

TABLE 4. Powers of M_S, M_L and \widetilde{T} for three selected alternatives and different sample sizes. $\alpha = 0.05, 10,000$ MC for M_S and M_L , and 2000 MC for \widetilde{T} .

Alternative	Test	n=25	n = 50	n = 100	n = 200
$P\delta(0.7, 1.5)$	M_S	23	45	76	98
The first group	M_L	22	42	74	97
in Table 2	\widetilde{T}	34	59	90	100
PP(0.1, 1.1, 6.1)	M_S	31	46	69	92
The second group	M_L	32	50	76	96
in Table 2	\widetilde{T}	30	46	72	95
$A_4(5,1,0.08)$	M_S	29	49	81	99
A new alternative	M_L	33	62	94	100
from Table 3	\widetilde{T}	17	28	54	89

To illustrate power curves of compared tests under increasing sample size we have selected three alternatives, one from each group considered above. For all sample sizes we took the same parameters $d(n), D, K, \delta_n, \alpha, \lambda_0$ as for n = 50. The results are shown in Table 4.

Concluding, one can say that the new tests perform comparable sensitivity to \widetilde{T} as well as to I and V^* while M_L preserves stable and high sensitivity for a much wider class of various types of alternatives. So, if 'less smooth' departure from Poissonity is expected, then the test M_L may be recommended.

4. APPENDIX

Description of alternatives. Probability mass functions of distributions different from P_{λ} will be denoted by p_j for integer $j \ge 0$.

U(m; l), m < l – the uniform distribution on the set $\{m, m+1, \ldots, l\}$.

b(m,p) – the binomial distribution with parameters $m \in \mathbb{N}$ and $p \in (0,1)$.

nb(m,p) – the negative binomial distribution with parameters $m \in \mathbb{N}$ and $p \in (0,1)$.

 $P\delta(\varepsilon,\lambda)$ – the mixture $\varepsilon P_{\lambda} + (1-\varepsilon)\delta_0$ of the Poisson distribution and the Dirac delta in zero.

 $PP(\varepsilon,\lambda_1,\lambda_2)$ – the mixture $\varepsilon P_{\lambda_1}+(1-\varepsilon)P_{\lambda_2}$ of two Poisson distributions.

 $GP(\lambda, \vartheta)$ – the generalized Poisson distribution with parameters $\lambda > 0, -\lambda < \vartheta < 0, \vartheta > -1$ and probability mass function given by

$$p_j = \frac{\lambda(\lambda + \vartheta j)^{j-1} e^{-\lambda - \vartheta j}}{i!}, \quad j = 0, 1, \dots, \lfloor -\lambda/\vartheta \rfloor.$$

 $GP\delta(\lambda, \vartheta, \varepsilon)$ – the mixture $(1 - \varepsilon)GP(\lambda, \vartheta) + \varepsilon\delta_0$ of the generalized Poisson distribution and the Dirac delta in zero.

 $PBM(\varepsilon,m,p)$ – the mixture $\varepsilon P_{mp} + (1-\varepsilon)b(m,p)$ of the Poisson distribution and the binomial distribution with the same mean.

 $GH(\lambda_1, \lambda_2)$ – the generalized Hermite distribution, i.e. the distribution of $Y_1 + 2Y_2$, where Y_1, Y_2 are independent random variables with Poisson distributions $P_{\lambda_1}, P_{\lambda_2}$.

TG(p) – the geometric distribution with parameter p, i.e. with probability mass function $p_j = p(1-p)^{j-1}, \ j=1,2,\ldots$

BB(m,p,q) – the beta-binomial distribution with parameters $m \in \mathbb{N}, \ p,q > 0$, i.e. with probability mass function given by

$$p_j = \int_0^1 {m \choose j} x^j (1-x)^{m-j} B_{pq}(x) dx, \quad j = 0, 1, \dots, m,$$

where $B_{pq}(x)$ is the density of the beta distribution with parameters p, q.

 $PSS(\lambda_1, \lambda_2)$ – the Poisson-stopped-sum distribution, i.e. the distribution of the sum $\sum_{i=1}^{N} Y_i$, where N has P_{λ_1} distribution while Y_i are i.i.d. with Poisson P_{λ_2} distribution and N is independent of Y_i 's.

Tests for comparison. All tests described below reject the null hypothesis for large values of the corresponding statistics.

- T defined by the statistic $T = \sqrt{n} \left[\sum_{j=0}^{m} \left(|F_n(j) F(j, \overline{X})| + F(j, \overline{X}) \right) \right]$ $+\sqrt{n}(\overline{X}-m-1)$, where $m=\max_{1\leqslant i\leqslant n}X_i$, F_n is the empirical distribution function and $F(k, \lambda)$ is the distribution function of P_{λ} (the notation as in Klar [6]).
- I defined by the statistic $I = \sqrt{n} \max_{1 \le k \le m} \left| \sum_{j=0}^k \left(F_n(j) F(j, \overline{X}) \right) \right|$, where m, F_n and $F(k,\lambda)$ are as above (cf. Klar [6], the notation after Gürtler and Henze [3]). • V^* defined by the statistic $V=n^{-3}\overline{X}^{-1.45}\sum_{j=0}^{2m-2}a_j^2$, where

$$a_j = \sum_{l=0}^{j+2} l(2l-j-3)N_l N_{j+2-l}$$

while N_j is the number of observations equal to j (cf. Nakamura and Pérez-Abreu [9]).

R code for tests proposed in the present paper is available at: http://prac.im.pwr.wroc.pl/ inglot/badania.html

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