

Matrix operators on symmetric Kähler domains.
References: A. Boussejra and H. Airault,

1 The basic tools

The representation

$$T_g F(Z) = k'_g(Z)^\gamma F(k_g(Z))$$

$$Z \in D \rightarrow k_g(Z) \in D, \quad g \in G$$

Hua's classical matrix

$$Z = (z_{ij}) \rightarrow \partial_Z = \left(\frac{\partial}{\partial z_{uj}} \right)$$

Matrix multiplication

Let A, B be two square matrices and denote

$$\begin{aligned} \mathcal{V}_1 &= AB - BA, & \mathcal{V}_2 &= i(AB + BA) \\ \mathcal{V}_3 &= B - ABA, & \mathcal{V}_4 &= i(B + ABA) \end{aligned}$$

Then $\text{trace}(\mathcal{V}_1 \bar{\mathcal{V}}_1 - \mathcal{V}_2 \bar{\mathcal{V}}_2 + \mathcal{V}_3 \bar{\mathcal{V}}_3 + \mathcal{V}_4 \bar{\mathcal{V}}_4) =$

$$2 \text{trace}((I - A\bar{A})\bar{B}(I - \bar{A}A)B)$$

and $\mathcal{V}_1^2 - \mathcal{V}_2^2 + \mathcal{V}_3^2 + \mathcal{V}_4^2 = 0$.

Define

$$\begin{aligned} \mathcal{H}(\mathcal{V}_1) &= 0, & \mathcal{H}(\mathcal{V}_2) &= i Id \\ \mathcal{H}(\mathcal{V}_3) &= A, & \mathcal{H}(\mathcal{V}_4) &= -i A \end{aligned}$$

then $\text{trace}(\mathcal{H}(\mathcal{V}_2)\mathcal{V}_2 + \mathcal{H}(\mathcal{V}_3)\mathcal{V}_3 + \mathcal{H}(\mathcal{V}_4)\mathcal{V}_4) = 0$ and $\text{trace}(\overline{\mathcal{H}(\mathcal{V}_2)}\mathcal{V}_2 + \overline{\mathcal{H}(\mathcal{V}_3)}\mathcal{V}_3 + \overline{\mathcal{H}(\mathcal{V}_4)}\mathcal{V}_4) =$

$$2 \text{trace}[(I - \bar{A}A)BA]$$

2 Objectives

(1) The construction of measures on Kähler manifolds. We have already the volume measure (if the manifold is finite dimensional).

(2) Obtain Laplacian and Ornstein-Uhlenbeck operators on a Kähler manifold D from the infinitesimal holomorphic representation of a group G on D .

(3) Study the measures on D which are invariant with respect to the Laplacian and Ornstein-Uhlenbeck operators. The volume measure is an invariant measure for the Laplacian.

(4) Provide an approach to the construction of invariant measures on infinite dimensional manifolds.

3 Our present approach:

3.1 The vector fields of the infinitesimal holomorphic representation of G are the coefficients of Hua's matrix operators

We give examples of Kähler manifolds D and a group G of holomorphic transformations of D where the vector fields of the infinitesimal holomorphic representation of G are the coefficients of Hua's matrix operators and can be calculated with matrix products.

In this talk, I shall restrict to the manifold D of symmetric matrices Z such that $I - Z\bar{Z} > 0$ and to submanifolds of D .

Theorem 1 The vector fields of the infinitesimal representation are given by the matrix products

$$(i) \quad \mathcal{V}_t = (Z\partial_Z^\epsilon - \partial_Z^\epsilon Z) + i(Z\partial_Z^\epsilon + \partial_Z^\epsilon Z)$$

$$(ii) \quad \mathcal{V}_p = (\partial_Z^\epsilon - Z\partial_Z^\epsilon Z) + i(\partial_Z^\epsilon + Z\partial_Z^\epsilon Z)$$

where ∂_Z^ϵ is a Hua type matrix operator which has to be defined. The Laplacian and Ornstein-Uhlenbeck operators on D can be calculated by making products of the matrices

$$\mathcal{V}_1 = (Z\partial_Z^\epsilon - \partial_Z^\epsilon Z) = (a_{jk}), \quad \mathcal{V}_2 = i(Z\partial_Z^\epsilon + \partial_Z^\epsilon Z) = (b_{jk})$$

$$\mathcal{V}_3 = (\partial_Z^\epsilon - Z\partial_Z^\epsilon Z) = (\phi_{jk}), \quad \mathcal{V}_4 = i(\partial_Z^\epsilon + Z\partial_Z^\epsilon Z) = (\psi_{jk})$$

and their complex conjugates.

\mathcal{V}_1 is antisymmetric, thus $\sum_{j,k} a_{jk}\bar{a}_{jk} = -\text{trace}(\mathcal{V}_1\bar{\mathcal{V}}_1)$,

$\mathcal{V}_2, \mathcal{V}_3, \mathcal{V}_4$ are symmetric, thus

$$\sum_{j,k} b_{jk}\bar{b}_{jk} = \text{trace}(\mathcal{V}_2\bar{\mathcal{V}}_2)$$

$$\sum_{j,k} \phi_{jk}\bar{\phi}_{jk} + \sum_{j,k} \psi_{jk}\bar{\psi}_{jk} = \text{trace}(\mathcal{V}_3\bar{\mathcal{V}}_3) + \text{trace}(\mathcal{V}_4\bar{\mathcal{V}}_4)$$

then

$$\begin{aligned} & \text{trace}(\mathcal{V}_1\bar{\mathcal{V}}_1) - \text{trace}(\mathcal{V}_2\bar{\mathcal{V}}_2) + \text{trace}(\mathcal{V}_3\bar{\mathcal{V}}_3) + \text{trace}(\mathcal{V}_4\bar{\mathcal{V}}_4) \\ & = 2 \text{trace} [(I - Z\bar{Z})\bar{\partial}_Z(I - \bar{Z}Z)\partial_Z] \end{aligned}$$

It links Hua's expression of the Laplacian

$$\text{trace} [(I - Z\bar{Z})\bar{\partial}_Z(I - \bar{Z}Z)\partial_Z]$$

to the vector fields of the infinitesimal holomorphic representation of G .

3.2 The vector field $\mathcal{V} = \text{trace}((I - \bar{Z}Z)\partial_Z^\epsilon Z)$ in the Ornstein-Uhlenbeck operator

∂_Z^ϵ is the Hua type matrix operator to be defined.

How to obtain \mathcal{V} from the operators

$$(i) \quad \mathcal{V}_{\mathbf{t}} = (Z\partial_Z^\epsilon - \partial_Z^\epsilon Z) + i(Z\partial_Z^\epsilon + \partial_Z^\epsilon Z)$$

$$(ii) \quad \mathcal{V}_{\mathbf{p}} = (\partial_Z^\epsilon - Z\partial_Z^\epsilon Z) + i(\partial_Z^\epsilon + Z\partial_Z^\epsilon Z)$$

To a matrix operator $\mathcal{T} = (v_{ij})$ where v_{ij} are vector fields, we associate the matrix of functions

$$\mathcal{H}(\mathcal{T}) = (h(v_{ij}))$$

where

$$h(v)(z) = \frac{d}{dt}\bigg|_{t=0} k'_{g_t}(z)$$

is the derivative of the holomorphic jacobian of the map $z \rightarrow k_{g_t}(z)$, t is a real parameter, $g_t \in G$, $g_0 = e$ and $v = \frac{d}{dt}\big|_{t=0} g_t$.

We find

$$\begin{aligned} \mathcal{H}(Z\partial_Z^\epsilon - \partial_Z^\epsilon Z) &= 0, \quad \mathcal{H}(Z\partial_Z^\epsilon + \partial_Z^\epsilon Z) = Id, \\ \mathcal{H}(\partial_Z^\epsilon - Z\partial_Z^\epsilon Z) &= Z, \quad \mathcal{H}(\partial_Z^\epsilon + Z\partial_Z^\epsilon Z) = -Z \end{aligned}$$

Let $\mathcal{U} = \overline{\mathcal{H}(Z\partial_Z^\epsilon + \partial_Z^\epsilon Z)}(Z\partial_Z^\epsilon + \partial_Z^\epsilon Z) +$

$$\overline{\mathcal{H}(\partial_Z^\epsilon - Z\partial_Z^\epsilon Z)}(\partial_Z^\epsilon - Z\partial_Z^\epsilon Z) + \overline{\mathcal{H}(\partial_Z^\epsilon + Z\partial_Z^\epsilon Z)}(\partial_Z^\epsilon + Z\partial_Z^\epsilon Z)$$

then

$$\text{trace } \mathcal{U} = \text{trace}[(I - \bar{Z}Z)\partial_Z^\epsilon Z] = \mathcal{V}$$

3.3 The representation of the group of holomorphic transformations $k_g : Z \rightarrow k_g(Z)$ on D and the holomorphic Jacobian determinant $k'_g(Z)$

Let D be the manifold of $n \times n$ symmetric matrices Z such that $I - Z\bar{Z} > 0$.

The group G of matrices $g = \begin{pmatrix} A & B \\ \bar{B} & \bar{A} \end{pmatrix}$ operates transitively on D with

$$\begin{aligned} W &= k_g(Z) = (AZ + B)(\bar{B}Z + \bar{A})^{-1} \\ &= (AZ + B)M^{-1} \quad \text{where } M(Z) = \bar{B}Z + \bar{A} \end{aligned}$$

We have

$$I - \overline{k_g(Z)}k_g(Z) = (M^*)^{-1}(I - \overline{Z}Z)M^{-1}$$

The volume element on D is

$$dv = \frac{dc_1 \overline{dc_1} \cdots}{\det(I - \overline{Z}Z)^{n+1}}$$

and the holomorphic Jacobian is such that

$$|k'_g(Z)|^2 = \frac{\phi(k_g(Z))}{\phi(Z)} \quad \text{with} \quad \phi(Z) = (\det(I - \overline{Z}Z))^{n+1}$$

This does not stay true for a submanifold \mathcal{M} of D . We shall give an example of \mathcal{M} in the set of 3×3 matrices such that

$$|k'_g(Z)|^2 = \frac{\phi(k_g(Z))}{\phi(Z)} \quad \text{with} \quad \phi(Z) = \lambda_1(Z)^2 \lambda_2(Z)^3 \lambda_3(Z)^3$$

where $\lambda_1(Z), \lambda_2(Z), \lambda_3(Z)$ are the three eigenvalues of $I - \overline{Z}Z$.

Since $I - \overline{k_g(Z)}k_g(Z) = (M^*)^{-1}(I - \overline{Z}Z)M^{-1}$, we deduce

$$\det(I - \overline{W}W) = \frac{\det(I - \overline{Z}Z)}{|\det M(Z)|^2}$$

We can write this identity in the following way

$$\prod_j \lambda_j(W) = \frac{\prod_j \lambda_j(Z)}{\prod_j |\nu_j(Z)|^2}$$

where $\lambda_1(Z), \lambda_2(Z), \dots, \lambda_n(Z)$ are the eigenvalues of $I - \overline{Z}Z$ and $\nu_1(Z), \nu_2(Z), \dots, \nu_n(Z)$ are the eigenvalues of $M(Z)$.

For our example of Kähler submanifold \mathcal{M} of 3×3 symmetric matrices in D , we prove

$$\lambda_1(W) = \frac{\lambda_1(Z)}{|\nu_1(Z)|^2} \quad \text{and} \quad \lambda_2(W)\lambda_3(W) = \frac{\lambda_2(Z)\lambda_3(Z)}{|\nu_2(Z)|^2|\nu_3(Z)|^2}$$

3.4 Find invariant measures on the Kähler submanifolds \mathcal{M} of D .

Consider the subgroup $G_{\mathcal{M}}$ of G and acting on \mathcal{M} . Denote $Z = (z_1, z_2, \dots)$ the independent variables in Z and $W = (w_1, w_2, \dots)$ the independent variables in W and denote $k'_g(Z)$ the holomorphic Jacobian determinant of the map

$$k_g; \quad Z = (z_1, z_2, \dots) \rightarrow W = (w_1, w_2, \dots)$$

1- We wish to find probability measures μ on \mathcal{M} such that for $g \in G_{\mathcal{M}}$,

$$\int_{\mathcal{M}} |k'_g(Z)|^\gamma |F(k_g(Z))|^2 \mu_\gamma(dZ) = \int_{\mathcal{M}} |F(Z)|^2 \mu_\gamma(dZ)$$

2- One of the difficulties for submanifolds is to determine the Jacobian determinant $k'_g(Z)$ when the number p of independent variables in the $n \times n$ symmetric matrix Z is less than $n(n+1)/2$. For a submanifold \mathcal{M} of D , let $G_{\mathcal{M}}$ be the subgroup of G and acting on \mathcal{M} .

- (1) Is there any relation between $k'_g(Z)$, $\det(\overline{B}Z + \overline{A})$ and $\frac{\det(I - \overline{W}W)}{\det(I - \overline{Z}Z)}$ as it was the case for D ?
- (2) The calculation of the holomorphic Jacobian $k'_g(Z)$ is delicate.
- (3)- How to relate the independent vector fields

$$\frac{\partial}{\partial z_1}, \frac{\partial}{\partial z_2}, \dots$$

to the independent vector fields $\frac{\partial}{\partial w_1}, \frac{\partial}{\partial w_2}, \dots$, that is how to calculate the holomorphic Jacobian matrix of the map $k_g(Z)$?

4 The condition $dZ = M^{tr}[dW]M$

Let $W = (AZ + B)(\overline{B}Z + \overline{A})^{-1}$ then

$$dW = (M^{-1})^{tr}(dZ)M^{-1} \quad \text{with} \quad M = \overline{B}Z + \overline{A}$$

If the coefficients of the matrix Z are all distinct, we have independent variables and

$$\partial_W = M \partial_Z M^{tr}$$

where $\partial_W = (\frac{\partial}{\partial w_{jk}})$ and $\partial_Z = (\frac{\partial}{\partial z_{jk}})$ are the classical Hua's matrices operators.

The relation $\partial_W = M \partial_Z M^{tr}$ is no more valid if the coefficients of Z are not independent variables. In the case of the domain of symmetric matrices Z , it remains true if we replace ∂_Z and ∂_W respectively by the operators matrices

$$\widehat{\partial}_Z = ((1 + \delta_{jk}) \frac{\partial}{\partial z_{jk}}) \quad \text{and} \quad \widehat{\partial}_W = ((1 + \delta_{jk}) \frac{\partial}{\partial w_{jk}})$$

When there are less than $n(n+1)/2$ independent variables, we have to make another choice for $\widehat{\partial}_Z$ and $\widehat{\partial}_W$ and it depends on the domain.

Remark In the case of the domain of symmetric matrices Z , in order to obtain the Laplacian as a trace of product of matrices, Hua makes a rescaling of the coefficients of Z , keeping the matrix symmetric, instead of changing ∂_Z . This amounts to the same.

4.1 From $dZ = M^{tr}[dW]M$ to $\overset{\infty}{\partial}_W = M \overset{\infty}{\partial}_Z M^{tr}$

The matrix operator $\overset{\infty}{\partial}_Z$ depends on the manifold \mathcal{M} .

We say that \mathcal{M} is a linear submanifold of D if it consists of matrices $Z \in D$ such that $ZJ_1 = J_2Z$ where J_1 and J_2 are two real invertible matrices.

Let Z and W in the same linear submanifold \mathcal{M} of D and assume that $dZ = M^{tr}[dW]M$. The following lemma can be applied to some examples of linear submanifolds of D .

Lemma. Assume that (C) is satisfied:

(C) :There is a partition $A_1 \cup A_2 \cup \dots \cup A_k$ of the indices of the coefficients of the matrices W and Z such that when $(j, p) \in A_r$ then $z_{jp} = b_r$ and $w_{jp} = c_r$. If $r \neq s$, then b_r and b_s (c_r and c_s) are independent variables. Let $n_{jp} = n_r$ be the cardinal of A_r . Then $\overset{\infty}{\partial}_W = M \overset{\infty}{\partial}_Z M^{tr}$ with the matrix operator $\overset{\infty}{\partial}_Z = (\frac{1}{n_{jp}} \frac{\partial}{\partial z_{jp}})$.

5 The Kähler manifold of symmetric matrices Z such that $I - Z\bar{Z} > 0$ and submanifolds.

A Kähler manifold (D, ω) is a complex manifold D and ω is a smooth differential (1,1)-form on D which can be written

$$\omega = i \sum_{j,k} \frac{\partial^2 \log K}{\partial c_j \partial \bar{c}_k} dc_j \wedge d\bar{c}_k, \quad c = (c_1, c_2, \dots) \in D$$

where the Kähler potential K is a real positive function. Then ω is closed ($d\omega = 0$).

To ω is associated the riemannian metric

$$ds^2 = - \sum_{j,k} \frac{\partial^2 \log K}{\partial c_j \partial \bar{c}_k} dc_j d\bar{c}_k$$

5.1 We take as Kähler manifold D the set of symmetric matrices such that $I - Z\bar{Z} > 0$

with Kähler potential

$$K(Z, \bar{Z}) = \det(I - \bar{Z}Z)$$

In that case, the independant coefficients in $Z = (z_{ij})$ are

$$(c_1, c_2, \dots) = (z_{ij})_{i \leq j}$$

For the manifold D , the Bergman kernel is

$$[\det(I - \bar{Z}Z)]^\alpha$$

see for example Hua's book. Thus for D , the Kähler metric defined with the potential $K(Z, \bar{Z}) = \det(I - \bar{Z}Z)$ is the same as the Bergman metric.

**5.2 We take as Kähler manifold \mathcal{M} a submanifold of D .
In \mathcal{M} , we still have symmetric matrices such that $I - Z\bar{Z} > 0$, but not all**

On \mathcal{M} , we shall take again as Kähler potential $K(Z, \bar{Z}) = \det(I - \bar{Z}Z)$. But for a submanifold, $[\det(I - \bar{Z}Z)]^\alpha$ may be different from the Bergman potential as shown by our examples.

Recall: Bergman kernel, let $f : \Omega_1 \rightarrow \Omega_2$, f holomorphic, then

$$\det J_{\mathbf{C}}f(z)K_{\Omega_2}(f(z), f(\xi))\overline{\det J_{\mathbf{C}}f(\xi)} = K_{\Omega_1}(z, \xi)$$

In our example of \mathcal{M} of 3×3 matrices, we prove

$$|k'_g(Z)|^2 = \frac{\phi(k_g(Z))}{\phi(Z)} \quad \text{with} \quad \phi(Z) = \lambda_1(Z)^2 \lambda_2(Z)^3 \lambda_3(Z)^3$$

where $\lambda_1(Z)$, $\lambda_2(Z)$, $\lambda_3(Z)$ are the three eigenvalues of $I - \bar{Z}Z$. Then $[\det(I - \bar{Z}Z)]^\alpha$ is not the Bergman kernel and the metric obtained with

$$K(Z, \bar{Z}) = \det(I - \bar{Z}Z)$$

is different from the Bergman metric.

5.3 The (1,1)-form ω and the metric when the Kähler potential is $K(Z, \bar{Z}) = \det(I - \bar{Z}Z)$

In that case, the Kähler differential (1,1)-form ω and the metric have nice expressions thanks to the relation

$$\log \det(I - \bar{Z}Z) = \text{trace} \log(I - \bar{Z}Z)$$

Then (see for example BSM 2012-HA)

$$\begin{aligned} p_{jk} &= \frac{\partial^2}{\partial c_j \partial \bar{c}_k} \log \det(I - \bar{Z}Z) \\ &= -\text{trace}[(I - \bar{Z}Z)^{-1} \frac{\partial \bar{Z}}{\partial \bar{c}_k} \times (I - Z\bar{Z})^{-1} \frac{\partial Z}{\partial c_j}] \end{aligned}$$

Since $dZ = (dz_{ij})$ is given by $dZ = \sum_k \frac{\partial Z}{\partial c_k} dc_k$, the closed two-form ω and the riemannian metric ds^2 are

$$\begin{aligned}\omega &= i \operatorname{trace} [(I - \bar{Z}Z)^{-1} d\bar{Z} \wedge (I - Z\bar{Z})^{-1} dZ] \\ ds^2 &= - \sum_{j,k} p_{jk} dc_j d\bar{c}_k = \operatorname{trace} [(I - \bar{Z}Z)^{-1} d\bar{Z} (I - Z\bar{Z})^{-1} dZ]\end{aligned}$$

5.4 The (1,1)-form ω and the metric for a submanifold

For a submanifold \mathcal{M} of D , we take the same Kähler potential

$$K(Z, \bar{Z}) = \det(I - \bar{Z}Z)$$

but there are less independent variables:

then dZ is different, it gives a closed form $\omega_{\mathcal{M}}$ which is different from ω and a metric $ds_{\mathcal{M}}^2$ different from the ds^2 on D and also different from the Bergman metric on \mathcal{M} .

For submanifolds \mathcal{M} , formulas

$$\begin{aligned}\omega_{\mathcal{M}} &= i \operatorname{trace} [(I - \bar{Z}Z)^{-1} d\bar{Z} \wedge (I - Z\bar{Z})^{-1} dZ] \\ &= i \operatorname{trace} [\bar{\Omega} \wedge \Omega]\end{aligned}$$

and $ds_{\mathcal{M}}^2 = - \sum_{j,k} p_{jk} dc_j d\bar{c}_k = \operatorname{trace} [(I - \bar{Z}Z)^{-1} d\bar{Z} (I - Z\bar{Z})^{-1} dZ]$ are still valid but with a different dZ .

Assume that there is a group $G_{\mathcal{M}}$ of transformations $Z \rightarrow W$ on \mathcal{M} such that

$$dZ = M^{tr} dW M$$

and $I - \bar{W}W = (M^*)^{-1} (I - \bar{Z}Z) M^{-1}$ with $W = k_g(Z)$, the closed (1,1)-form $\omega_{\mathcal{M}}$ and the metric $ds_{\mathcal{M}}^2$ are invariant under the transformations of the group $G_{\mathcal{M}}$.

The volume element is obtained with

$$\omega_{\mathcal{M}} \wedge \omega_{\mathcal{M}} \wedge \dots$$

From $dZ = M^{tr} dW M$, we deduce operators matrices $\hat{\partial}_W$ and $\hat{\partial}_Z$ such that

$$\hat{\partial}_W = M \hat{\partial}_Z M^{tr}$$

Thus the operator

$$\Delta_{\mathcal{M}} = \operatorname{trace} [(I - Z\bar{Z}) \overline{\hat{\partial}_Z} (I - \bar{Z}Z) \hat{\partial}_Z]$$

is invariant under the transformations of $G_{\mathcal{M}}$.

For our examples of submanifolds \mathcal{M} , $\Delta_{\mathcal{M}}$ is the Laplacian associated to the metric

$$ds_{\mathcal{M}}^2 = \text{trace} [(I - \bar{Z}Z)^{-1} d\bar{Z}(I - Z\bar{Z})^{-1} dZ]$$

but $ds_{\mathcal{M}}^2$ is not the Bergman metric corresponding to the group of transformations $G_{\mathcal{M}}$.

6 The group G of holomorphic transformations of D and the operator T_g on holomorphic functions on D .

$$W = k_g(Z) = (AZ + B)(\bar{B}Z + \bar{A})^{-1} \quad g = \begin{pmatrix} A & B \\ \bar{B} & \bar{A} \end{pmatrix} \in G$$

with $\bar{A}^{tr}A - B^{tr}\bar{B} = I$ and $\bar{A}^{tr}B = B^{tr}\bar{A}$.

$$T_g F(Z) = k'_g(Z)^\gamma F(k_g(Z)), \quad \gamma \in \mathbf{R}$$

Since

$$|k'_g(Z)|^2 = \frac{\phi(k_g(Z))}{\phi(Z)} \quad \text{with} \quad \phi(Z) = (\det(I - Z^*Z))^\alpha$$

the operator T_g is unitary in $Hol_{\mathbf{C}}^2(d\mu)$ for the measure

$$d\mu_\gamma = [\det(I - \bar{Z}Z)]^{\alpha(\gamma-1)} d\lambda(Z)$$

The volume element on D is up to a multiplicative constant, equal to

$$d\mu_0 = \frac{d\lambda(Z)}{\phi(Z)}$$

6.1 The Lie algebra \mathfrak{g} of G is the real vector space,

$$\begin{aligned} \mathfrak{g} &= \left\{ \begin{pmatrix} \alpha & \beta \\ \bar{\beta} & \bar{\alpha} \end{pmatrix} \text{ with } \alpha + \alpha^* = 0 \text{ and } \beta = \beta^{tr} \right\} \\ \mathfrak{g} &= \left\{ \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix}, \alpha^* + \alpha = 0 \right\} \oplus \left\{ \begin{pmatrix} 0 & \beta \\ \bar{\beta} & 0 \end{pmatrix}, \beta = \beta^{tr} \right\} \\ \mathfrak{g} &= \mathfrak{t} \oplus \mathfrak{p} \quad (\text{Cartan decomposition}) \end{aligned}$$

6.2 The holomorphic vector fields on D .

Let $X = \begin{pmatrix} \alpha & \beta \\ \bar{\beta} & \bar{\alpha} \end{pmatrix} \in \mathfrak{g}$. Denote $W_t(X) = g_t$ a curve on G such that

$$g_t = \begin{pmatrix} A_t & B_t \\ \bar{B}_t & \bar{A}_t \end{pmatrix} \in G, \quad g_0 = I \quad \text{and} \quad \frac{d}{dt}\Big|_{t=0} g_t = X$$

$$\text{where} \quad A_t = I + t\alpha + o(t^2) \quad \text{and} \quad B_t = t\beta + o(t^2)$$

Then

$$W_t = k_{g_t}(Z) = (Z + t(\alpha Z + \beta) + o(t^2))(I - t(\bar{\alpha} + \bar{\beta}Z) + o(t^2))$$

$$\frac{d}{dt}\Big|_{t=0} k_{g_t}(Z) = \frac{d}{dt}\Big|_{t=0} (A_t Z + B_t)(\bar{B}_t Z + \bar{A}_t)^{-1} = \alpha Z - Z\bar{\alpha} + \beta - Z\bar{\beta}Z$$

Let F be a complex-valued holomorphic function on D , ($\frac{\partial F}{\partial \bar{z}} = 0$). The holomorphic vector fields $V(X)$ are given by

$$(V(X)F)(Z) = \frac{d}{dt}\Big|_{t=0} F(k_{g_t}(Z))$$

$$\frac{d}{dt}\Big|_{t=0} F(W_t) = \sum_{p \leq q} \frac{\partial F}{\partial z_{pq}} \frac{d}{dt}\Big|_{t=0} (W_t)_{pq} \quad \text{where} \quad W_t = k_{g_t}(Z)$$

7 A basis (e_j) of \mathfrak{t} and the vector fields $V(e_j)$.

The Lie algebra \mathfrak{t} has dimension n^2 as real vector space.

Basis: $H_j = \begin{pmatrix} d_j & 0 \\ 0 & \bar{d}_j \end{pmatrix}$ where $d_j = iE_{jj}$, $j = 1, \dots, n$,

$$X_{jk} = \begin{pmatrix} E_{jk} - E_{kj} & 0 \\ 0 & E_{jk} - E_{kj} \end{pmatrix}$$

$$Y_{jk} = \begin{pmatrix} i(E_{jk} + E_{kj}) & 0 \\ 0 & -i(E_{jk} + E_{kj}) \end{pmatrix}, \quad 1 \leq j < k \leq n$$

Vector fields:

$$V(H_j) = [(d_j Z + Z d_j) \partial_Z]_{jj} = iz_{jj} \frac{\partial}{\partial z_{jj}} + i(Z \partial_Z^{tr})_{jj}$$

$$V(X_{jk}) = (Z \partial_Z^{tr})_{kj} - (Z \partial_Z^{tr})_{jk} + z_{jk} \frac{\partial}{\partial z_{jj}} - z_{kj} \frac{\partial}{\partial z_{kk}}, \quad j < k$$

$$V(Y_{jk}) = i[(Z \partial_Z^{tr})_{kj} + (Z \partial_Z^{tr})_{jk} + z_{kj} \frac{\partial}{\partial z_{jj}} + z_{jk} \frac{\partial}{\partial z_{kk}}], \quad j < k$$

8 The vector fields $V(H_j)$, $V(X_{jk})$, $V(Y_{jk})$ as coefficients of a Hua's matrix operator

To the matrix $Z = (z_{ij}) \in D$, we associate the Hua's matrix operator,

$$\widehat{\partial}_Z = \frac{1}{2} \left((1 + \delta_{ij}) \frac{\partial}{\partial z_{ij}} \right) \quad \text{where } \delta_{ij} = 0 \text{ if } i \neq j \text{ and } \delta_{jj} = 1$$

then

$$Z\widehat{\partial}_Z - \widehat{\partial}_Z Z = -\frac{1}{2} \begin{pmatrix} 0 & V(X_{12}) & V(X_{13}) & \cdots \\ -V(X_{12}) & 0 & V(X_{23}) & \cdots \\ -V(X_{13}) & -V(X_{23}) & 0 & \cdots \\ \cdots & \cdots & \cdots & \cdots \end{pmatrix}$$

$$Z\widehat{\partial}_Z + \widehat{\partial}_Z Z = -\frac{i}{2} \begin{pmatrix} 2V(H_1) & V(Y_{12}) & V(Y_{13}) & \cdots \\ V(Y_{12}) & 2V(H_2) & V(Y_{23}) & \cdots \\ V(Y_{13}) & V(Y_{23}) & 2V(H_3) & \cdots \\ \cdots & \cdots & \cdots & \cdots \end{pmatrix}$$

8.1 Corollaries

$$\sum_{e_j \in \mathfrak{t}} B(e_j, e_j)^{-1} V(e_j)^2 = 2 \operatorname{trace} (Z\widehat{\partial}_Z Z\widehat{\partial}_Z)$$

and

$$\begin{aligned} D_{\mathfrak{t}} &=: \sum_{e_j \in \mathfrak{t}} B(e_j, e_j)^{-1} V(e_j) \overline{V(e_j)} = -2 \sum_{j,k} (Z\widehat{\partial}_Z)_{kj} (\overline{Z\widehat{\partial}_Z})_{kj} \\ &= -2 \operatorname{trace} (\overline{Z} Z \widehat{\partial}_Z \widehat{\partial}_{\overline{Z}}) \end{aligned}$$

where $B(X, Y) = \operatorname{trace} (XY)$ is the Killing form on \mathfrak{g} .

9 A basis (e_j) of the Lie subalgebra \mathfrak{p} and the vector fields $V(e_j)$.

The basis: $A_j = \begin{pmatrix} 0 & a_j \\ a_j & 0 \end{pmatrix}$, $B_j = \begin{pmatrix} 0 & b_j \\ -b_j & 0 \end{pmatrix}$ where $a_j = \operatorname{diag}(0, \dots, 0, 1, 0, \dots; 0)$, $b_j = ia_j$, $j = 1, \dots, n$ and A_{jk}, B_{jk} with $(1 \leq j < k \leq n)$:

$$A_{jk} = \begin{pmatrix} 0 & E_{jk} + E_{kj} \\ E_{jk} + E_{kj} & 0 \end{pmatrix},$$

$$B_{jk} = \begin{pmatrix} 0 & i(E_{jk} + E_{kj}) \\ -i(E_{jk} + E_{kj}) & 0 \end{pmatrix}$$

9.1 The vector fields

For $j < k$, let $\beta_{jk} = E_{jk} + E_{kj}$ and $a_j = \frac{1}{2}(E_{jj} + E_{jj}) = \frac{1}{2}\beta_{jj}$. Then

$$\begin{aligned} V(A_{jk}) &= \frac{\partial}{\partial z_{jk}} - \sum_{p \leq q} (Z\beta_{jk}Z)_{pq} \frac{\partial}{\partial z_{pq}} \\ V(B_{jk}) &= i \left(\frac{\partial}{\partial z_{jk}} + \sum_{p \leq q} (Z\beta_{jk}Z)_{pq} \frac{\partial}{\partial z_{pq}} \right) \\ V(A_j) &= \frac{\partial}{\partial z_{jj}} - \frac{1}{2} \sum_{p \leq q} (Z\beta_{jj}Z)_{pq} \frac{\partial}{\partial z_{pq}} \\ V(B_j) &= i \left(\frac{\partial}{\partial z_{jj}} + \frac{1}{2} \sum_{p \leq q} (Z\beta_{jj}Z)_{pq} \frac{\partial}{\partial z_{pq}} \right) \end{aligned}$$

9.2 The vector fields $V(A_j)$, $V(B_j)$, $V(A_{jk})$, $V(B_{jk})$ as coefficients of a Hua's matrix operator

For the symmetric matrices $\mathcal{V}^A = \widehat{\partial}_Z - Z\widehat{\partial}_Z Z$ and $\mathcal{V}^B = i(\widehat{\partial}_Z + Z\widehat{\partial}_Z Z)$, it holds

$$\begin{aligned} \widehat{\partial}_Z - Z\widehat{\partial}_Z Z &= \begin{pmatrix} 2V(A_1) & V(A_{12}) & V(A_{13}) & \cdots \\ V(A_{12}) & 2V(A_2) & V(A_{23}) & \cdots \\ V(A_{13}) & V(A_{23}) & 2V(A_3) & \cdots \\ \cdots & & & \ddots \end{pmatrix} \\ i(\widehat{\partial}_Z + Z\widehat{\partial}_Z Z) &= \begin{pmatrix} 2V(B_1) & V(B_{12}) & V(B_{13}) & \cdots \\ V(B_{12}) & 2V(B_2) & V(B_{23}) & \cdots \\ V(B_{13}) & V(B_{23}) & 2V(B_3) & \cdots \\ \cdots & & & \ddots \end{pmatrix} \end{aligned}$$

9.3 Corollaries

$$\begin{aligned} &\frac{1}{4} \sum_{j < k} V(A_{jk})^2 + V(B_{jk})^2 + \frac{1}{2} \sum_j V(A_j)^2 + V(B_j)^2 \\ &= -\frac{1}{2} \text{trace} (Z\widehat{\partial}_Z Z\widehat{\partial}_Z) \\ &\frac{1}{4} \sum_{j < k} V(A_{jk})\overline{V(A_{jk})} + V(B_{jk})\overline{V(B_{jk})} + \frac{1}{2} \sum_j V(A_j)\overline{V(A_j)} + V(B_j)\overline{V(B_j)} \\ &= \frac{1}{4} \text{trace} (\widehat{\partial}_Z \widehat{\partial}_Z + \overline{Z} Z \widehat{\partial}_Z Z \overline{Z} \widehat{\partial}_Z) \end{aligned}$$

Notation: We have put $\widehat{\partial}_Z = 2\widehat{\partial}_Z$.

9.4 Identification of $\sum_j B(e_j, e_j)^{-1}l(e_j)\overline{l(e_j)}$ with the Laplacian

$$\sum_j B(e_j, e_j)^{-1}l(e_j)\overline{l(e_j)} = \frac{1}{4} \text{trace} [(I - \bar{Z}Z)\widehat{\partial}_Z(I - Z\bar{Z})\widehat{\partial}_{\bar{Z}}]$$

where $\widehat{\partial}_Z = \partial_Z + D_Z$ and $D_Z = \text{diagonal}[\frac{\partial}{\partial z_{11}}, \dots, \frac{\partial}{\partial z_{jj}}, \dots]$ is a diagonal matrix operator.

10 Linear Kähler submanifolds of D .

We say that \mathcal{M} is a linear submanifold of D if it consists of matrices $Z \in D$ such that $ZJ_1 = J_2Z$ where J_1 and J_2 are two real invertible matrices. We have considered three examples:

Example 1. $Z \in \mathcal{M}$ if $JZ = ZJ$ where

$$J = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}. \text{ Then } Z = \begin{pmatrix} z_1 & z_2 & z_4 \\ z_2 & z_3 & z_2 \\ z_4 & z_2 & z_1 \end{pmatrix}.$$

Example 2. $Z \in \mathcal{M}_-$ if $JZ = ZJ$ where

$$J = \begin{pmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}. \text{ Then } Z = \begin{pmatrix} z_1 & z_2 & z_3 \\ z_2 & z_1 & -z_3 \\ z_3 & -z_3 & z_4 \end{pmatrix}.$$

In Examples 1 and 2, $J_1 = J_2 = J$ and $J^2 = Id$.

Example 3. Extending Example 1, let $Z \in \mathcal{M}$ if $Z = \begin{pmatrix} z_1 & z_2 & z_4 \\ z_2 & z_3 & \lambda z_2 \\ z_4 & \lambda z_2 & \lambda^2 z_1 \end{pmatrix}$,

$$J = \begin{pmatrix} 0 & 0 & \lambda \\ 0 & 1 & 0 \\ \frac{1}{\lambda} & 0 & 0 \end{pmatrix}, \text{ then } J^{tr}ZJ = Z \text{ and } \lambda \text{ is fixed.}$$

11 Condition $dZ = M^{tr}[dW]M$ for linear submanifolds of D .

Example 1. $Z = \begin{pmatrix} z_1 & z_2 & z_4 \\ z_2 & z_3 & z_2 \\ z_4 & z_2 & z_1 \end{pmatrix}$, $dZ = M^{tr}[dW]M$ implies $M = \begin{pmatrix} m_1 & m_2 & m_4 \\ \kappa & m_3 & \kappa \\ m_4 & m_2 & m_1 \end{pmatrix}$

and $\widehat{\partial}_W = M\widehat{\partial}_Z M^{tr}$ with the matrix operator

$$\widehat{\partial}_Z = \begin{pmatrix} \frac{1}{2} \frac{\partial}{\partial z_1} & \frac{1}{4} \frac{\partial}{\partial z_2} & \frac{1}{2} \frac{\partial}{\partial z_4} \\ \frac{1}{4} \frac{\partial}{\partial z_2} & \frac{\partial}{\partial z_3} & \frac{1}{4} \frac{\partial}{\partial z_2} \\ \frac{1}{2} \frac{\partial}{\partial z_4} & \frac{1}{4} \frac{\partial}{\partial z_2} & \frac{1}{2} \frac{\partial}{\partial z_1} \end{pmatrix}$$

Example 2. $Z = \begin{pmatrix} z_1 & z_2 & z_3 \\ z_2 & z_1 & -z_3 \\ z_3 & -z_3 & z_4 \end{pmatrix}, \quad M = \begin{pmatrix} m_1 & m_2 & m_3 \\ m_2 & m_1 & -m_3 \\ \delta & -\delta & m_4 \end{pmatrix}$

$$\widehat{\partial}_W = M \widehat{\partial}_Z M^{tr} \quad \text{with} \quad \widehat{\partial}_Z = \begin{pmatrix} \frac{1}{2} \frac{\partial}{\partial z_1} & \frac{1}{2} \frac{\partial}{\partial z_2} & \frac{1}{4} \frac{\partial}{\partial z_3} \\ \frac{1}{2} \frac{\partial}{\partial z_2} & \frac{1}{2} \frac{\partial}{\partial z_1} & -\frac{1}{4} \frac{\partial}{\partial z_3} \\ \frac{1}{4} \frac{\partial}{\partial z_3} & -\frac{1}{4} \frac{\partial}{\partial z_3} & \frac{\partial}{\partial z_4} \end{pmatrix}$$

Example 3. $Z = \begin{pmatrix} z_1 & z_2 & z_4 \\ z_2 & z_3 & \lambda z_2 \\ z_4 & \lambda z_2 & \lambda^2 z_1 \end{pmatrix}, \quad dZ = M^{tr}[dW]M$ implies $M =$

$$\begin{pmatrix} m_1 & \lambda m_2 & \lambda^2 m_4 \\ \delta_2 & m_3 & \lambda \delta_2 \\ m_4 & m_2 & m_1 \end{pmatrix} \text{ and } \widehat{\partial}_W = M \widehat{\partial}_Z M^{tr} \text{ with } \widehat{\partial}_Z = \text{constant} \begin{pmatrix} 2 \frac{\partial}{\partial z_1} & \frac{\partial}{\partial z_2} & 2 \frac{\partial}{\partial z_4} \\ \frac{\partial}{\partial z_2} & 4 \frac{\partial}{\partial z_3} & \frac{1}{\lambda} \frac{\partial}{\partial z_2} \\ 2 \frac{\partial}{\partial z_4} & \frac{1}{\lambda} \frac{\partial}{\partial z_2} & \frac{2}{\lambda^2} \frac{\partial}{\partial z_1} \end{pmatrix}.$$

In Examples 1 and 2, we know the group of holomorphic transformations on \mathcal{M} and its Lie algebra. With the same methods that we have used on D , we find the vector fields of the infinitesimal representation and we verify that they are given by $Z \widehat{\partial}_Z - \widehat{\partial}_Z Z$, $i(Z \widehat{\partial}_Z + \widehat{\partial}_Z Z)$, $\widehat{\partial}_Z - Z \widehat{\partial}_Z Z$ and $i(\widehat{\partial}_Z + Z \widehat{\partial}_Z Z)$.

Example 1, $ZJ = JZ$,

$$Z = \begin{pmatrix} z_1 & z_2 & z_4 \\ z_2 & z_3 & z_2 \\ z_4 & z_2 & z_1 \end{pmatrix}, \quad \widehat{\partial}_Z = \text{constant} \begin{pmatrix} 2 \frac{\partial}{\partial z_1} & \frac{\partial}{\partial z_2} & 2 \frac{\partial}{\partial z_4} \\ \frac{\partial}{\partial z_2} & 4 \frac{\partial}{\partial z_3} & \frac{1}{\lambda} \frac{\partial}{\partial z_2} \\ 2 \frac{\partial}{\partial z_4} & \frac{1}{\lambda} \frac{\partial}{\partial z_2} & \frac{2}{\lambda^2} \frac{\partial}{\partial z_1} \end{pmatrix}.$$

The group $G_{\mathcal{M}}$ is the set of matrices $\begin{pmatrix} A & B \\ B & A \end{pmatrix}$ such that $\overline{A}^{tr} A - B^{tr} \overline{B} = I$, $\overline{A}^{tr} B = B^{tr} \overline{A}$, $JA = AJ$, $JB = BJ$.

$$Z \widehat{\partial}_Z - \widehat{\partial}_Z Z = \begin{pmatrix} 0 & -\frac{V(\alpha)}{4} & 0 \\ \frac{V(\alpha)}{4} & 0 & \frac{V(\alpha)}{4} \\ 0 & -\frac{V(\alpha)}{4} & 0 \end{pmatrix}$$

$$i(Z \widehat{\partial}_Z + \widehat{\partial}_Z Z) = \begin{pmatrix} \frac{V(\gamma(1))}{2} & \frac{V(\gamma(2))}{4} & \frac{V(\gamma(4))}{2} \\ \frac{V(\gamma(2))}{4} & V(\gamma(3)) & \frac{V(\gamma(2))}{4} \\ \frac{V(\gamma(4))}{2} & \frac{V(\gamma(2))}{4} & \frac{V(\gamma(1))}{2} \end{pmatrix}$$

$$\widehat{\partial}_Z - Z \widehat{\partial}_Z Z = \begin{pmatrix} \frac{V(\beta(1))}{2} & \frac{V(\beta(2))}{4} & \frac{V(\beta(4))}{2} \\ \frac{V(\beta(2))}{4} & V(\beta(3)) & \frac{V(\beta(2))}{4} \\ \frac{V(\beta(4))}{2} & \frac{V(\beta(2))}{4} & \frac{V(\beta(1))}{2} \end{pmatrix}$$

$$i(\widehat{\partial}_Z + Z \widehat{\partial}_Z Z) = \begin{pmatrix} \frac{V(i\beta(1))}{2} & \frac{V(i\beta(2))}{4} & \frac{V(i\beta(4))}{2} \\ \frac{V(i\beta(2))}{4} & V(i\beta(3)) & \frac{V(i\beta(2))}{4} \\ \frac{V(i\beta(4))}{2} & \frac{V(i\beta(2))}{4} & \frac{V(i\beta(1))}{2} \end{pmatrix}$$

Then $\sum_j \frac{1}{B(e_j, e_j)} l(e_j) \overline{l(e_j)} = \text{trace}((I - \overline{Z}Z) \widehat{\partial}_Z (I - Z\overline{Z}) \widehat{\partial}_{\overline{Z}})$ where $l(e_j)$ are the the vector fields of the infinitesimal representation.

Recall:

To a matrix operator $\mathcal{T} = (v_{ij})$ where v_{ij} are vector fields, we associate the matrix of functions

$$\mathcal{H}(\mathcal{T}) = (h(v_{ij})) \quad \text{where} \quad h(v)(z) = \frac{d}{dt}|_{t=0} k'_{g_t}(z)$$

is the derivative of the holomorphic jacobian of $z \rightarrow k_{g_t}(z)$, t is a real parameter, $g_t \in G_{\mathcal{M}}$, $g_0 = e$ and $v = \frac{d}{dt}|_{t=0} g_t$.

For the manifold \mathcal{M} ,

$$\mathcal{H}(Z\hat{\partial}_Z - \hat{\partial}_Z Z) = 0,$$

$$\mathcal{H}(Z\hat{\partial}_Z + \hat{\partial}_Z Z) = 3 Id,$$

$$\mathcal{H}(\hat{\partial}_Z - Z\hat{\partial}_Z) = -3Z + \frac{z_1 - z_4}{2}(\beta(1) - \beta(4)),$$

$$\mathcal{H}(\hat{\partial}_Z + Z\hat{\partial}_Z) = 3Z - \frac{z_1 - z_4}{2}(\beta(1) - \beta(4))$$

$$\text{where } \beta(1) - \beta(4) = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

$$\text{Let } \mathcal{U} = \frac{\mathcal{H}(Z\partial_Z^\epsilon + \partial_Z^\epsilon Z)}{\mathcal{H}(\partial_Z^\epsilon - Z\partial_Z^\epsilon Z)}(Z\partial_Z^\epsilon + \partial_Z^\epsilon Z) - \frac{\mathcal{H}(\partial_Z^\epsilon + Z\partial_Z^\epsilon Z)}{\mathcal{H}(\partial_Z^\epsilon - Z\partial_Z^\epsilon Z)}(\partial_Z^\epsilon - Z\partial_Z^\epsilon Z)$$

$$\text{then } \text{trace}(\mathcal{U}) = 6 \text{trace}[(I - \bar{Z}Z)\partial_Z^\epsilon Z] + (\bar{z}_1 - \bar{z}_4) \text{trace}[(\beta(1) - \beta(4))Z\partial_Z^\epsilon Z] = \mathcal{V}.$$

We deduce $\mathcal{V} := \sum_j B(e_j, e_j)^{-1} \overline{h(e_j)} l(e_j) =$

$$\text{trace}[(I - \bar{Z}Z)\hat{\partial}_Z Z] - \text{constant}(\bar{z}_1 - \bar{z}_4)(z_1 - z_4)^2 \left(\frac{\partial}{\partial z_1} - \frac{\partial}{\partial z_4} \right)$$

12 Example 3: We do not know the group of transformations

In Example 3, $Z = \begin{pmatrix} z_1 & z_2 & z_4 \\ z_2 & z_3 & \lambda z_2 \\ z_4 & \lambda z_2 & \lambda^2 z_1 \end{pmatrix}$, let W be of the same kind. By identifying coefficients, we can calculate the conditions on the matrix M in order

that $dZ = M^{tr}[dW]M$. This implies that $M = \begin{pmatrix} m_1 & \lambda m_2 & \lambda^2 m_4 \\ \delta_2 & m_3 & \lambda \delta_2 \\ m_4 & m_2 & m_1 \end{pmatrix}$.

Then the condition

$$dZ = M^{tr}[dW]M$$

permits by identification of coefficients, to calculate $\hat{\partial}_Z$ such that

$$\hat{\partial}_W = M \hat{\partial}_Z M^{tr}$$

We find $\mathring{\partial}_Z = \text{constant} \begin{pmatrix} 2\frac{\partial}{\partial z_1} & \frac{\partial}{\partial z_2} & 2\frac{\partial}{\partial z_4} \\ \frac{\partial}{\partial z_2} & 4\frac{\partial}{\partial z_3} & \frac{1}{\lambda}\frac{\partial}{\partial z_2} \\ 2\frac{\partial}{\partial z_4} & \frac{1}{\lambda}\frac{\partial}{\partial z_2} & \frac{2}{\lambda^2}\frac{\partial}{\partial z_1} \end{pmatrix}$.

Without knowing a group of holomorphic transformations on \mathcal{M} , with the matrix operators $Z\mathring{\partial}_Z - \mathring{\partial}_Z Z$,

$i(Z\mathring{\partial}_Z + \mathring{\partial}_Z Z)$, $\mathring{\partial}_Z - Z\mathring{\partial}_Z Z$ and $\mathring{\partial}_Z + Z\mathring{\partial}_Z Z$, we can construct holomorphic vector fields $l(e_j)$. With the $l(e_j)$ obtained as the coefficients of the matrix operators do we have

$$\sum_j \frac{1}{B(e_j, e_j)} l(e_j) \overline{l(e_j)} = \text{trace}((I - \overline{Z}Z)\mathring{\partial}_Z(I - Z\overline{Z})\mathring{\partial}_{\overline{Z}})$$

12.1 The volume element on \mathcal{M} in Example 1.

Let $Z = \begin{pmatrix} z_1 & z_2 & z_4 \\ z_2 & z_3 & z_2 \\ z_4 & z_2 & z_1 \end{pmatrix}$ and let $\lambda_1(Z) = (u_1 - u_4)(Z)$, $\lambda_2(Z)$, $\lambda_3(Z)$ be the

eigenvalues of $I - \overline{Z}Z = \begin{pmatrix} u_1 & \overline{u_2} & u_4 \\ u_2 & u_3 & u_2 \\ u_4 & \overline{u_2} & u_1 \end{pmatrix}$, it holds

$$|k'_{g_t}(Z)|^2 = \frac{\phi(k_{g_t}(Z))}{\phi(Z)} \quad \text{with} \quad \phi(Z) = \lambda_1(Z)^2 \lambda_2(Z)^3 \lambda_3(Z)^3$$

The volume element on \mathcal{M} is

$$dv = \lambda_1(Z)^{-2} \lambda_2(Z)^{-3} \lambda_3(Z)^{-3} dz_1 \overline{dz_1} \cdots dz_4 \overline{dz_4}$$

The representation $T_g F(Z) = F(k_g(Z))$ is unitary in $Hol_{\mathbb{C}}^2(dv)$.

13 Question

What happens if we take the metric associated to the Bergman kernel in a general context. Let G denote the identity component of the group of all biholomorphic mappings of the domain and let $J(g, z)$ be the Jacobian determinant of the biholomorphic map $z \rightarrow g.z$. Do we have a similar expression for the Laplacian with the holomorphic vector fields of the representation? and what about the anti-holomorphic (holomorphic) gradient vector field and the complex Ornstein-Uhlenbeck operators on the domain?