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AN APPROACH TO THE FORMULA $L = \lambda V$ VIA THE THEORY OF STATIONARY POINT PROCESSES ON A SPACE OF COMPACT SUBSETS OF R^k

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1. Introduction

Much attention has been drawn to the queueing formula $L = \lambda V$; see [1],[2],[3],[5],[10],[11],[12]. In this context L means "average queue", λ means "intensity of arrivals" and V means "average delay in queue". In this note we point out that the formula $L = \lambda V$ is valid for stationary processes of random compact sets $\underline{\mu}$ in R^k . Informally speaking it is a collection of random compact sets strewn over R^k in a stationary manner. A formal definition will be given in Section 4. In this context L means "average number of sets covering zero", λ means intensity of $\underline{\mu}$, and V means "average volume of a typical set". Clearly concepts of the intensity and average volume of a typical set need explanations and they are studied in Sections 5 and 6. The formula $L = \lambda V$ is studied in Section 6. The proof of $L = \lambda V$ is based on the behaviour of sample path and applies Nguyen-Zessin's ergodic theorem for point processes; see [8]. Finally in Section 7 we deal with the number of sets from a stationary process of random compact sets $\underline{\mu}$ overlapping a compact set K . The special case of such a problem was considered in [6], and recently, in this setting, was independently studied by Stoyan [12].

2. Preliminaries

Throughout the paper we denote the k -dimensional Euclidean space by R^k and the Borel σ -field of subsets of R^k by B^k . The set of all non-negative real numbers we denote by R_+ . For a topological space E we denote by BE the Borel σ -field of subsets of E . The open ball in a metric space E with the center x and the radius r we denote by $B(E, x, r)$. The complement of a set A is A^c . The indicator function of a set A is $1_A(x)$. The following notations and convention are used:

$$(0,1)^k = (0,1) \times \dots \times (0,1) \in B^k,$$

$$|B| = \int_B dx, \quad B \in B^k,$$

$$\sum_{i=0}^{\infty} \frac{x^i}{i!} = e^x.$$

3. Random elements associated with point process

We follow Kallenberg [4] for the definition of random measures or point processes. Let E be a locally compact second countability Hausdorff topological space (LCS). Let $M(E)$ be the class of measures μ such that $\mu(V) < \infty$, for any bounded V and $C(E)$ be the class of continuous functions f with compact support. We can make $M(E)$ into a Polish space with convergence $\mu_n \rightarrow \mu$ iff $\int f d\mu_n \rightarrow \int f d\mu$ for all $f \in C(E)$. The subset $M(E)$ of integer valued measures in $M(E)$ is Borel.

Let (Ω, F, P) be a probability space.

Definition 3.1:

A measurable mapping

$$\underline{\mu}: (\Omega, F) \rightarrow (M(E), BM(E))$$

is said to be a random measure on E . If $\Omega = M(E)$, $F = BM(E)$ and $\underline{\mu}(\omega) = \omega$ then $\underline{\mu}$ is called the canonical random measure on E . The canonical random measure identifies with the probability space $(M(E), BM(E), P)$.

Definition 3.2:

A measurable mapping

$$\underline{\nu}: (\Omega, F) \rightarrow (N(E), BN(E))$$

is said to be a point process on E . If $\Omega = N(E)$, $F = BN(E)$ $\underline{\nu}(\omega) = \omega$ then $\underline{\nu}$ is called the canonical point process on E . The canonical point process identifies with the probability space $(N(E), BN(E), P)$.

Consider a Polish space A and a locally compact secondcountability group E . There is given on A a family of automorphisms $\{\sigma_x\}$; $x \in E$ full-filling

- (a) $\sigma_x \circ \sigma_y = \sigma_{x+y}$, $x, y \in E$ (group property),
- (b) the mapping $A \times E \ni (\alpha, x) \rightarrow \sigma_x \alpha \in M$ is measurable.

On $M(E)$ we define a family of automorphisms $\{\tau_x\}$, $x \in E$ by

$$\tau_x \mu(B) = \mu(B+x), \quad x \in E, \quad B \in BE.$$

Denote for $(\alpha, \mu) \in A \times M(E)$

$$\tau_x(\alpha, \mu) = (\sigma_x \alpha, \tau_x \mu), \quad x \in E.$$

Let $\underline{\alpha}$ be a random element on a probability space (Ω, F, P) assuming values at A . Let $\underline{\mu}$ be a random measure on E defined on the probability space (Ω, F, P) .

Definition 3.3:

The pair $(\underline{\alpha}, \underline{\mu})$ is called the random element associated with random measure. The $(\underline{\alpha}, \underline{\mu})$ is said to be stationary if

$$P \circ (\underline{\alpha}, \underline{\mu})^{-1} \circ \tau_x = P \circ (\underline{\alpha}, \underline{\mu})^{-1}$$

or

$$(3.1) \quad P \circ \tau_x = P, \quad x \in E,$$

where $P = P \circ (\underline{\alpha}, \underline{\mu})^{-1}$ is the distribution of $(\underline{\alpha}, \underline{\mu})$.

In the case when $\underline{\mu}$ is a point process we adopt the abbreviation REAPP for $(\underline{\alpha}, \underline{\mu})$.

We aim now to define the Palm distribution of P . It is a simply modification of the definition from [7], where the Palm distribution was defined not for the random elements associated with random measure but for the random measure. From now on P is stationary that is (3.1) holds. Define a measure $\lambda(\cdot)$ on (E, BE) by

$$(3.2) \quad \lambda(B) = E \underline{\mu}(B), \quad B \in BE.$$

We assume that $\lambda(\cdot)$ is non-zero and $\lambda(B) < \infty$ for bounded B . Then $\lambda(\cdot)$ is a Haar measure on (E, BE) . Let $g: E \rightarrow R_+$ be such that

$$\int_E g(x) \lambda(dx) = 1$$

and set for $F \in B(A \times M(E))$

$$P^0(F) = \int_{A \times M(E)} \int_E g(x) 1_F \circ \tau_x(\alpha, \mu) \mu(dx) P(d\alpha \times d\mu).$$

Clearly P^0 is a probability measure. We shall call it as the Palm distribution of P .

Theorem 3.1 (Mecke [7]):

The Palm distribution P^0 of P is the only probability on $A \times M(E)$ such that for all nonnegative $B(A \times M(E) \times E)$ -measurable functions $z((\alpha, \mu), x)$

$$(3.5) \quad \int_{A \times M(E)} \int z((\alpha, \mu), x) \mu(dx) P(da \times d\mu) = \int_{A \times M(E)} \int z(T_{-x}(\alpha, \mu), x) \lambda(dx) P^0(da \times d\mu) .$$

Let $(\underline{\alpha}, \underline{\nu})$ be a stationary REAPP and suppose that $\underline{\nu}$ is a point process on R^k . In such a case $E = R^k$, $\lambda(dx) = \lambda dx$, where λ is the intensity of $\underline{\nu}$ and dx is the Lebesgue measure on R^k . Denote

$$A \times N^0(R^k) = \{(\alpha, \mu) \in A \times N(R^k) : \mu(\{0\}) \geq 1\} .$$

We have the following corollary.

Corollary:

If P^0 is the Palm distribution of a REAPP $(\underline{\alpha}, \underline{\nu})$, where $\underline{\nu}$ is a point process on R^k then

$$P^0(A \times N^0(R^k)) = 1 .$$

Proof. Set in (3.5)

$$z((\alpha, \mu), x) = \begin{cases} 1, & \mu(\{x\}) \geq 1, \quad x \in (0, 1)^k, \\ 0, & \text{otherwise.} \end{cases}$$

Recall also the following definition.

Definition 3.4:

It is said that a point process $\underline{\nu}$ on E is without multiple points if

$$P(\{\omega : \underline{\nu}(\omega)(\{x\}) \leq 1, \quad x \in E\}) = 1 .$$

4. Processes of random sets.

Let K be the space of all compact sets in R^k endowed with the Hausdorff metric given by

$$h(K_1, K_2) = \max_{x \in K_2} \kappa(x, K_1), \quad \sup_{x \in K_1} \kappa(x, K_2) .$$

Here $\kappa(x, K)$ denotes the distance from x to K in the Euclidean metric. It is known (see e.g. [6]) that (K, h) is LCS.

Let $u(K)$ and $\rho(K)$ denote the center and the radius of the ball circumscribing a compact set $K \in R^k$. The ball circumscribing a compact set K is a ball of the smallest volume containing K . The following argument shows existence and uniqueness. Define the function $r(x) = \min\{t : B(R^k, x, t) \supset K\}$, which is clearly continuous. Thus there exists x_0 such that $r(x_0) = \min_{x \in K} r(x)$. If there exists another ball $B(R^k, y_0, r(x_0)) \supset K$, $x_0 \neq y_0$ then also

$$B(R^k, (x_0 - y_0)/2, (r^2(x_0) - (\|x_0 - y_0\|/2)^2)^{1/2}) \supset K .$$

However in such a case $(r^2(x_0) - (\|x_0 - y_0\|/2)^2)^{1/2} < r(x_0)$ which is impossible.

The mappings $u : K \rightarrow R^k$ and $\rho : K \rightarrow R_+$ are continuous and

$$(4.1) \quad u(K+x) = u(K) + x ,$$

$$(4.2) \quad \rho(K+x) = \rho(K) , \quad x \in R^k , \quad K \in K .$$

Consider a canonical point process $\underline{\mu}$ on K , that is a probability space $(M(K), \mathcal{B}(K), \mathbb{P})$. We assume that $\underline{\mu}$ is stationary. It was shown in [4], Lemma 2.5, that

$$(4.3) \quad \underline{\mu} = \sum_i 1_{\{K_i\}} ,$$

where $\underline{K}_i, i=0, 1, \dots$ is a sequence of r.e.'s assuming values at K .

Definition 4.1:

The point process $\underline{\mu}$ is said to be a process of random sets.

Using representation (4.3) define random measures

$$(4.4) \quad \underline{\mu}_\rho = \sum_i \rho(K_i) 1_{\{u(K_i)\}} ,$$

$$(4.5) \quad \underline{\mu}_1 = \sum_i |K_i|^{-1} 1_{\{u(K_i)\}}$$

and the point process

$$(4.6) \quad \underline{\mu}^* = \sum_i 1_{\{u(K_i)\}} .$$

The measurability of mappings (4.4)-(4.6) it follows from the measurability of $\rho(K)$, $|K|$, $u(K)$. It is easy to show that $\underline{\mu}_\rho, \underline{\mu}_1, \underline{\mu}^*$ are stationary.

5. Intensity of $\underline{\mu}$.

Consider a stationary ergodic process of random sets $\underline{\mu}$. Let

$$(5.1) \quad \lambda = E \underline{\mu}^* ((0,1)^k)$$

be the intensity of $\underline{\mu}^*$. We assume $\lambda < \infty$, and $\underline{\mu}^*$ is without multiple points.

Definition 5.1.:

The value λ we call the intensity of the process of random sets $\underline{\mu}$.

The following definition was proposed in [8],[9].

Definition 5.2.:

A system of open, bounded, convex sets $\{Q_R\}$, $R > 0$ is said to be regular if

- (a) $Q_R \subset B(R^k, 0, R)$, $R > 0$,
- (b) there exists $k > 0$ and $R_0 > 0$ such that $|Q_R| > k|B(R^k, 0, R)|$, $R > R_0$.

In the sequel $\{Q_R\}$ always denotes a regular system of sets. The following proposition justifies Definition 5.1. Recall representation $\underline{\mu} = \int_1^1 K_1$.

Proposition 5.1:

The limit

$$(5.2) \quad \lim_{R \rightarrow \infty} \frac{\#\{i: K_1 \subset Q_R\}}{|Q_R|} = \lambda, \quad \text{a.s. } P.$$

Moreover

$$(5.3) \quad \lim_{R \rightarrow \infty} \frac{\#\{i: K_1 \cap Q_R \neq \emptyset\}}{|Q_R|} = \lambda, \quad \text{a.s. } P.$$

Proof. First we note that

$$\begin{aligned} \#\{i: K_1 \subset Q_R\} &, \\ \#\{i: u(K_1) \in Q_R\} & \end{aligned}$$

are random variables. It follows from the fact that

$$C = \{B \in K: B \subset Q_R\} \in BK \quad (\text{see [6]}),$$

$$\#\{i: K_1(\mu) \subset Q_R\} = \mu(C),$$

and that the mapping $\mu \rightarrow \mu(C)$ is measurable. Also $\#\{i: u(K_1) \in Q_R\}$ is a random variable because $\underline{\mu}^*$ is a point process and

$$(5.4) \quad \#\{i: u(K_1)(\mu) \in Q_R\} = \underline{\mu}^*(\mu)(Q_R).$$

To prove (5.2) it suffices to show

$$(5.5) \quad \lim_{R \rightarrow \infty} \frac{\#\{i: u(K_1) \in Q_R\}}{|Q_R|} = \lambda, \quad \text{a.s. } P$$

and

$$(5.6) \quad \lim_{R \rightarrow \infty} \left(\frac{\#\{i: u(K_1) \in Q_R\}}{|Q_R|} - \frac{\#\{i: K_1 \subset Q_R\}}{|Q_R|} \right) = 0, \quad \text{a.s. } P.$$

The existence of the limit in (5.5) is the immediate consequence of (5.4) and the Corollary 1 after Theorem 1 in [7].

To prove (5.6) define a subset of R^k

$$J^-(Q, r) = \{x \in Q: B(R^k, x, r) \subset Q\},$$

where $Q \in R^k$. Notice that $J^-(Q, r_1) \subset J^-(Q, r_2)$ whenever $r_1 \geq r_2$. We have for each $r > 0$

$$\begin{aligned} \{i: u(K_1) \in Q_R\} - \{i: K_1 \subset Q_R\} &\subset \\ \subset \{i: u(K_1) \in Q_R - J^-(Q_R, \rho(K_1))\} &= \\ = \{i: u(K_1) \in Q_R - J^-(Q_R, \rho(K_1)), 0 \leq \rho(K_1) \leq r\} \cup \\ \cup \{i: u(K_1) \in Q_R - J^-(Q_R, \rho(K_1)), \rho(K_1) > r\} &\subset \\ \subset \{i: u(K_1) \in Q_R - J^-(Q_R, r)\} \cup \{i: u(K_1) \in Q_R, \rho(K_1) > r\}. \end{aligned}$$

From Lemma 2 in [8] we have

$$\lim_{R \rightarrow \infty} \frac{|Q_R - J^-(Q_R, r)|}{|Q_R|} = 0.$$

hence by the Corollary 1 after Theorem 1 from [8]

$$\lim_{R \rightarrow \infty} \frac{\#\{i: u(\underline{K}_1) \in Q_R - J^-(Q_R, r)\}}{|Q_R|} = 0, \quad \text{a.s. } P.$$

The same corollary from [8] also provides

$$\begin{aligned} & \lim_{R \rightarrow \infty} \frac{\#\{i: u(\underline{K}_1) \in Q_{R, \rho}(\underline{K}_1) > r\}}{|Q_R|} \\ &= E(\#\{i: u(\underline{K}_1) \in (0, 1)^K, \rho(\underline{K}_1) > r\}), \quad \text{a.s. } P. \end{aligned}$$

Thus for completing the proof of (5.6) we remark that

$$\lim_{R \rightarrow \infty} E(\#\{i: u(\underline{K}_1) \in (0, 1)^K, \rho(\underline{K}_1) > r\}) = 0, \quad \text{a.s. } P$$

which follows from that

$$\begin{aligned} & \#\{i: u(\underline{K}_1) \in (0, 1)^K, \rho(\underline{K}_1) > r_1\} \leq \\ & \leq \#\{i: u(\underline{K}_1) \in (0, 1)^K, \rho(\underline{K}_1) > r_2\} \quad \text{if } r_1 \geq r_2 \end{aligned}$$

and

$$\begin{aligned} & \lim_{R \rightarrow \infty} E(\#\{i: u(\underline{K}_1) \in (0, 1)^K, \rho(\underline{K}_1) > r\}) \\ &= \lim_{r \rightarrow \infty} \lambda P_\rho^0(\{u: u(\{0\}) > r\}) = 0 \end{aligned}$$

where P_ρ^0 denotes the Palm distribution of the distribution of \underline{u} . This completes the proof of (5.2).

Now we prove (5.3). In view of (5.2) we need only to show

$$(5.7) \quad \lim_{R \rightarrow \infty} \left(\frac{\#\{i: \underline{K}_1 \cap Q_R \neq \emptyset\}}{|Q_R|} - \frac{\#\{i: \underline{K}_1 \subset Q_R\}}{|Q_R|} \right) = 0, \quad \text{a.s. } P.$$

However

$$\begin{aligned} & \{i: \underline{K}_1 \cap Q_R \neq \emptyset\} - \{i: \underline{K}_1 \subset Q_R\} \subset \\ & \subset \{i: u(\underline{K}_1) \in Q_{R, \rho}(\underline{K}_1) \cap Q_R^c \neq \emptyset\} \cup \{i: u(\underline{K}_1) \notin Q_{R, \rho}(\underline{K}_1) \cap Q_R \neq \emptyset\} \subset \\ & \subset \{i: u(\underline{K}_1) \in Q_R - J^-(Q_{R, \rho}(\underline{K}_1))\} \cup \\ & \cup \{i: u(\underline{K}_1) \in J^+(Q_{R, \rho}(\underline{K}_1)) - Q_R\}, \end{aligned}$$

where

$$J^+(Q, r) = \{x: B(R^k, x, r) \cap Q \neq \emptyset\}.$$

It was shown in the proof of (5.2) that

$$\lim_{R \rightarrow \infty} \frac{\#\{i: u(\underline{K}_1) \in Q_R - J^-(Q_{R, \rho}(\underline{K}_1))\}}{|Q_R|} = 0, \quad \text{a.s. } P.$$

In the similar way we can show that

$$\lim_{R \rightarrow \infty} \frac{\#\{i: u(\underline{K}_1) \in J^+(Q_{R, \rho}(\underline{K}_1)) - Q_R\}}{|Q_R|} = 0, \quad \text{a.s. } P.$$

which completes the proof of (5.3).

Remark:

We related with each K_1 the point $u(K_1)$ from $B(R^k, u(K_1), \rho(K_1))$. Sometimes it is more convenient to choose not $u(K_1)$ but another point $u'(K_1) \in B(R^k, u(K_1), \rho(K_1))$. This is just the case in queueing theory where K_1 are intervals in R^1 and $u'(K_1)$ is the left end-point of K_1 . We assume that the function u' is measurable. Then $\underline{u}' = \sum_i 1_{\{u'(K_1)\}}$ is a point process and

$$(5.8) \quad \lim_{R \rightarrow \infty} \frac{\underline{u}'(Q_R)}{|Q_R|} = \lambda, \quad \text{a.s. } P.$$

It follows from the inequalities

$$\#\{i: \underline{K}_1 \subset Q_R\} \leq \underline{u}'(Q_R) \leq \#\{i: B(R^k, u(\underline{K}_1), \rho(\underline{K}_1)) \cap Q_R \neq \emptyset\}$$

and

$$(5.9) \quad \lim_{R \rightarrow \infty} \left(\frac{\#\{i: B(R^k, u(\underline{K}_1), \rho(\underline{K}_1)) \cap Q_R \neq \emptyset\}}{|Q_R|} - \frac{\#\{i: \underline{K}_1 \subset Q_R\}}{|Q_R|} \right) = 0 \quad \text{a.s. } P.$$

The proof of (5.9) is similar to the proof of (5.7). Note also that \underline{u} need not to be stationary unless $u'(K) + x = u'(K+x)$, $x \in R^k$, $K \in K$.

6. Formula $L = \lambda V$.

Let \underline{u} be a canonical process of random sets in R^k . In other words \underline{u} is a point process on K and has representation $\underline{u} = \sum_i 1_{\{K_1\}}$.

Define $\underline{L}(t) : N(K) \rightarrow R_+$ by

$$\underline{L}(t) = \int_1^{t+1} \{K_1\}(\tau) \, d\tau, \quad t \in R^k,$$

i.e. $\underline{L}(t)$ is the number of sets from $\{K_1\}$ covering the point t . Let $\{\sigma_s\}, s \in R^k$ be a group of automorphisms on the class of functions $f : R^k \rightarrow R^1$ defined by

$$\sigma_s f(t) = f(t-s), \quad t, s \in R^k.$$

Lemma 6.1:

$\{L(t)\}, t \in R^k$ is a random process on $(N(K), \mathcal{B}(N(K)), \mathcal{P})$. Moreover if \mathcal{P} is stationary then $\{\underline{L}(t)\}$ is.

Proof. Measurability:

$$\{\mu : \underline{L}(s)(\mu) = k\} = \{\mu : \mu(K_{\{s\}}) = k\},$$

where as it was shown in [6]

$$K_{\{s\}} = \{K \in K : K \cap \{s\} \neq \emptyset\} \in \mathcal{B}K.$$

For the stationarity it suffices to point out that

$$\sigma_t \underline{L}(s)(\mu) = \underline{L}(s)(\tau_t \mu), \quad t, s \in R^k, \quad \mu \in N(K).$$

Consider a REAPP $(\underline{\mu}_1, \underline{\nu}^*)$, where $\underline{\mu}_1$ and $\underline{\nu}^*$ are defined in (4.5) and (4.6). Let \mathcal{P}_1 be the distribution $(\underline{\mu}_1, \underline{\nu}^*)$ and \mathcal{P}_1^0 its Palm distribution. Denote $\mathcal{P}_1^0(A) = \mathcal{P}_1^0(A \times N(R^k))$, $A \in R^k$. The measure $\lambda(\cdot)$ defined in (3.2) is λdx , where λ is the intensity of $\underline{\nu}^*$ and dx is the Lebesgue measure in R^k . Then for a non-negative $B(M(R^k) \times R^k)$ -measurable function $z(\mu, x)$ we have by (3.3)

$$(6.1) \quad \int_{M(R^k) \times N(R^k)} \int_{R^k} z(\mu, x) \nu(dx) \mathcal{P}_1(d\mu \times d\nu) \\ = \lambda \int_{M(R^k) \times R^k} \int_{R^k} z(\tau_{-x} \mu, x) dx \mathcal{P}_1^0(d\mu \times d\nu).$$

Lemma 6.2:

$$E \underline{\mu}_1(\{(0,1)^k\}) = \lambda E_{\mathcal{P}_1^0} \underline{\mu}_1(\{0\}),$$

where

$$E_{\mathcal{P}_1^0} \underline{\mu}_1(\{0\}) = \int_{M(R^k)} \mu(\{0\}) \mathcal{P}_1^0(d\mu).$$

Proof. Substitute to (6.1) the function

$$z(\mu, x) = \begin{cases} \mu(\{x\}), & x \in (0,1)^k, \\ 0, & \text{otherwise,} \end{cases}$$

Then

$$z(\tau_{-x} \mu, x) = \begin{cases} \mu(\{0\}), & x \in (0,1)^k, \\ 0, & \text{otherwise.} \end{cases}$$

Theorem 6.1:

If $\underline{\mu}$ is a stationary process of random sets with the finite intensity λ then

$$(6.2) \quad E \underline{\mu}(t) = \lambda E_{\mathcal{P}_1^0} |\underline{K}|,$$

where

$$E_{\mathcal{P}_1^0} |\underline{K}| = \int_{M(R^k)} \mu(\{0\}) \mathcal{P}_1^0(d\mu).$$

Proof. Denote

$$a(R) = \{i : u(\underline{K}_1^i) \in Q_R\}, \quad b(R) = \{i : \underline{K}_1^i \subset Q_R\}, \\ c(R) = \{i : \underline{K}_1^i \cap Q_R \neq \emptyset\}.$$

We have

$$\sum_{i \in a(R)} |\underline{K}_1^i| = \underline{\mu}_1(Q_R)$$

and from the Corollary 1 after Theorem 1 in [8]

$$\lim_{R \rightarrow \infty} \frac{\underline{\mu}_1(Q_R)}{|Q_R|} = E \underline{\mu}_1(\{(0,1)^k\} | J), \quad \text{a.s. } \mathcal{P},$$

where J denotes the σ -field of invariant sets with respect to $\{\tau_x\}$ on $(N(K), \mathcal{B}(K), \mathbb{P})$. Denote

$$\underline{y} = E[\underline{L}_1((0, 1^k)) | J].$$

From Lemma 6.1 we have

$$E \underline{y} = \lambda \int_{M(K)} v(\{0\}) P_1^0(d\mu)$$

The proof of the theorem is based on the inequality

$$(6.3) \quad \sum_{I \in \mathcal{B}(R)} |K_I| \leq \int \underline{L}(s) ds \leq \sum_{I \in \mathcal{C}(R)} |K_I|.$$

Thus it suffices to show that

$$(6.4) \quad \lim_{R \rightarrow \infty} \frac{\sum_{I \in \mathcal{B}(R)} |K_I|}{|Q_R|} = \underline{y}, \quad \text{a.s. } \mathbb{P},$$

$$(6.5) \quad \lim_{R \rightarrow \infty} \frac{\sum_{I \in \mathcal{C}(R)} |K_I|}{|Q_R|} = \underline{y}, \quad \text{a.s. } \mathbb{P}.$$

To prove (6.4) we find by a similar argument as in the proof of Proposition 5.1 that for each $r > 0$

$$\begin{aligned} 0 &\leq \sum_{I \in \mathcal{A}(R)} |K_I| - \sum_{I \in \mathcal{B}(R)} |K_I| \leq \\ &\leq \sum_{\{I: u(K_I) \in Q_R - J^-(Q_R, r)\}} |K_I| + \sum_{\{I: u(K_I) \in Q_R, \rho(K_I) > r\}} |K_I|. \end{aligned}$$

Lemma 2 and the Corollary 1 after Theorem 1 in [8] yields

$$\begin{aligned} &\lim_{R \rightarrow \infty} \frac{\sum_{\{I: u(K_I) \in Q_R - J^-(Q_R, r)\}} |K_I|}{|Q_R|} \\ &= \lim_{R \rightarrow \infty} \frac{\underline{\mu}_1(Q_R - J^-(Q_R, r))}{|Q_R|} = 0, \quad \text{a.s. } \mathbb{P}. \end{aligned}$$

They also provide existence of the limit

$$\lim_{R \rightarrow \infty} \frac{\sum_{\{I: u(K_I) \in Q_R, \rho(K_I) > r\}} |K_I|}{|Q_R|} =$$

$$= \lim_{R \rightarrow \infty} \frac{\sum_{I \in \mathcal{A}(R)} |K_I| 1_{(r, \infty)}(\rho(K_I))}{|Q_R|} = \underline{\phi}_r, \quad \text{a.s. } \mathbb{P}.$$

We have $\underline{\phi}_{r_1} \geq \underline{\phi}_{r_2}$, whenever $r_1 \leq r_2$ and $\lim_{R \rightarrow \infty} E \underline{\phi}_r = 0$ which yields $\lim_{R \rightarrow \infty} \underline{\phi}_r = 0$, a.s. \mathbb{P} . The proof of (6.5) is similar. Thus by (6.3)-(6.5),

$$\lim_{R \rightarrow \infty} \frac{\int \underline{L}(s) ds}{|Q_R|} = \underline{y}, \quad \text{a.s. } \mathbb{P}.$$

On the other hand from the stationarity of $\{\underline{L}(s)\}$, by the ergodic theorem

$$\lim_{R \rightarrow \infty} \frac{\int \underline{L}(s) ds}{|Q_R|} = \underline{y}, \quad \text{a.s. } \mathbb{P}$$

and

$$E \underline{y} = E \underline{L}(0).$$

Hence $\underline{y} = \underline{y}$, a.s. \mathbb{P} and

$$E \underline{y} = E \underline{L}(t) = E \underline{y} = \lambda E_0 |K_I|.$$

7. The number of sets overlapping a set K

We finish the paper contributing to the Matheron's textbook [6], where a special process of random sets was derived (namely stationary Poissonian).

Let $\underline{\mu}$ be a stationary canonical process of random sets. Recall that $\underline{\mu} = \sum 1_{(K_i)}$, where $K_i \rightarrow K$ are measurable. For a fixed set $K \in \mathcal{K}$ define

$$D = \{F \in \mathcal{K} : F \cap K \neq \emptyset\}.$$

From [6] it follows that $D \in \mathcal{B}K$. We ask for the expected value

$$(7.1) \quad E\#\{i: \underline{K}_1 \cap K \neq \emptyset\} = E\mu(D).$$

Let P_* denotes the distribution of the REAPP $(\underline{\mu}, \underline{\mu}^*)$ and P_0^* its Palm distribution. The marginal distribution we denote by $P_0^*(A) = \int_{R^k} P_0^*(A \times N(R^k))$, $A \in \mathcal{B}N(K)$. Assume that $0 < \lambda = E\mu^*(\{(0,1)^k\}) < \infty$ and that $\underline{\mu}^*$ is without multiple points.

To find $E\mu(D)$ we use formula (3.3) setting for $\mu = \sum_{i \in \underline{K}_1} 1_{\{K_i\}} \in N(K)$

$$z(\mu, x) = \begin{cases} 1, & K_1 \cap K \neq \emptyset, \quad u(K_1) = x, \\ 0, & \text{otherwise.} \end{cases}$$

Denote for $K, F \in K$

$$K \oplus F^\lambda = \{x \in R^k: K \cap (F+x) \neq \emptyset\}.$$

From [6] it follows that the mapping $K \in F \rightarrow F \oplus K \in K$ is measurable. Note that

$$\int_{R^k} z(\mu, x) \underline{\mu}^*(\mu)(dx) = \underline{\mu}^*(\mu)(D).$$

Consider the set

$$N_0^O(K) = \{\mu: \mu^*(\mu)(\{0\}) > 0\} \in \mathcal{B}N(K)$$

Define

$$M_1 = \{\mu: N_0^O(K): u(\underline{K}_1(\mu)) = 0\}, \quad i=0,1,\dots$$

and

$$\underline{g}(\mu) = \begin{cases} 1, & \text{if } \mu \in M_1, \\ 0, & \text{otherwise.} \end{cases}$$

Then $M_i, i=0,1,\dots$, are measurable and

$$\underline{K}(0)(\mu) = \underline{K} \underline{g}(\mu)(\mu)$$

is a random element. We have for $\mu \in N_0^O(K)$

$$\int_{R^k} z(\tau_{-x}, x) dx = |K \oplus K_0|.$$

Hence by (3.3)

$$E\mu(D) = \int_{N(K)} \int_{R^k} z(\mu, x) \underline{\mu}^*(\mu)(dx) P(d\mu) = \lambda \int_{N(K)} \int_{R^k} z(\tau_{-x}, \mu, x) dx P_0^*(d\mu) = \lambda \int_{K} |K \oplus F| P_0^O(dF),$$

where P_0^O is the distribution of random element $\underline{K}(0)$ on $(N(K), \mathcal{B}N(K), P_0^*)$. Thus we arrived at the relation

$$(7.2) \quad E\#\{i: \underline{K}_1 \cap K \neq \emptyset\} = \lambda \int_{N(K)} |K \oplus F| P_0^O(dF).$$

Note that if $K = \{0\}$ then (7.2) reduces to (6.2).

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SEQUENTIAL ESTIMATES OF A REGRESSION FUNCTION
BY ORTHOGONAL SERIES WITH APPLICATIONS IN DISCRIMINATION

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1. Introduction

Let (X, Y) be a pair of random variables. X takes values in a Borel set A , $A \subset \mathbb{R}^D$, whereas Y takes values in \mathbb{R} . Let f be the marginal Lebesgue density of X . Based on a sample $(X_1, Y_1), \dots, (X_n, Y_n)$ of independent observations of (X, Y) we wish to estimate the regression r of Y on X , i.e.

$$r(x) = E[Y|X=x].$$

Let $\{g_k\}$, $k=0, 1, 2, \dots$ be a complete orthonormal system defined on A , such that

$$|g_k(x)| \leq g_k \quad (1)$$

for all $x \in A$, where $\{g_k\}$ is a sequence of numbers. Define

$$h(x) = r(x)f(x).$$

We assume that functions h and f have the representations

$$h(x) \sim \sum_{k=0}^{\infty} a_k g_k(x), \quad (2)$$

Lecture Notes in Statistics

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