## PROBABILITY

# FAST APPROXIMATION OF SOLUTIONS OF SDE'S WITH OBLIQUE REFLECTION ON AN ORTHANT 

## KRZYSZTOF T. CZARKOWSKI (TORUŃ)

Abstract. We consider the discrete "fast" penalization scheme for SDE's driven by general semimartingale on orthant $\mathbb{R}_{+}^{d}$ with oblique reflection.

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## 1. INTRODUCTION

Suppose we have a $d$-dimensional semimartingale $Z=\left(Z^{1}, \ldots, Z^{d}\right)^{T}$, a Lipschitz continuous function $\sigma: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d} \otimes \mathbb{R}^{d}$, and a nonnegative $d \times d$ matrix $Q$ with zeros on the diagonal and spectral radius $\rho(Q)$ strictly less than one. Consider a $d$-dimensional stochastic differential equation (SDE) on orthant $\mathbb{R}_{+}^{d}$ with oblique reflection:

$$
\begin{equation*}
X_{t}=X_{0}+\int_{0}^{t} \sigma\left(X_{s-}\right) d Z_{s}+\left(1-Q^{T}\right) K_{t}, \quad t \in \mathbb{R}_{+} \tag{1.1}
\end{equation*}
$$

The equation of type (1.1) was introduced by Harrison and Reiman [9]. Later it was discussed by Dupuis and Ishi [5]. Czarkowski and Słomiński [3] introduced a numerical scheme for approximation of solution of SDE (1.1). In this paper we will define a new numerical scheme.

Throughout the paper we assume $\rho_{t}^{n}=\max \{i / n ; i \in \mathbb{N} \cup\{0\}, i / n \leqslant t\}$ and $Z_{t}^{(n)}$ is a discretization of $Z$, i.e. $Z_{t}^{(n)}=Z_{\rho_{t}^{n}} \rightarrow \mathcal{P}$ denotes convergence in probability, $\mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ means the space of càdlàg function $y: \mathbb{R}_{+} \rightarrow \mathbb{R}^{d}, \Delta y_{t}=$ $y_{t}-y_{t-}$ and $\omega_{1 / n}(y,[0, t])$ denotes the modulus of continuity of $y$ on $[0, t]$.

Let us define the function $[z]^{+}=\max \{z, 0\}$ for $z \in \mathbb{R}$ and, by analogy, the function $[z]^{+}=\left(\left[z^{1}\right]^{+}, \ldots,\left[z^{d}\right]^{+}\right)^{T}$ for $z=\left(z^{1}, \ldots, z^{d}\right)^{T} \in \mathbb{R}^{d}$. We will use the norm $\|Q\|=\max _{1 \leqslant i \leqslant d} \sum_{j=1}^{d} q_{i j}$.

In the simplest form our new numerical scheme is given in Section 3 (see (3.3)):

$$
x_{(i+1) / n}^{n}=x_{i / n}^{n}+\Delta y_{(i+1) / n}+\left(I-Q^{T}\right)\left[-x_{i / n}^{n}-\Delta y_{(i+1) / n}\right]^{+}
$$

In Section 3 we prove also convergence in some topology for the càdlàg and continuous function $y$ (see Theorem 3.1 and Corollary 3.1). We show that our scheme satisfies the Lipschitz property for the càdlàg function. In Section 4, we use the scheme for SDE driven by a semimartingale $Z_{t}$. In Section 5, we prove that

$$
E \sup _{s \leqslant t}\left|X_{s}^{n}-X_{s}\right|^{2 p}=\mathcal{O}\left(\left(\frac{\ln n}{n}\right)^{p}\right)
$$

for diffusion $X_{t}$.
The Appendix includes a description of some properties of $\Pi_{Q}$ projection on the orthant $\mathbb{R}_{+}^{d}$, which connects this paper with [3].

## 2. THE SKOROKHOD PROBLEM ON AN ORTHANT

Let $Q$ be a nonnegative matrix with zeros on the diagonal and spectral radius $\rho(Q)<1$ and let $y \in \mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ with $y_{0} \in \mathbb{R}_{+}^{d}$. Following Harrison and Reiman [9] a pair $(x, k) \in \mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{2 d}\right)$ is called a solution to the Skorokhod problem

$$
\begin{equation*}
x_{t}=y_{t}+\left(I-Q^{T}\right) k_{t}, \quad t \in \mathbb{R}_{+} \tag{2.1}
\end{equation*}
$$

on $\mathbb{R}_{+}^{d}$ associated with $y$, if (2.1) is satisfied and
$x_{t} \in \mathbb{R}_{+}^{d}, t \in \mathbb{R}_{+}$,
$k^{j}$ is nondecreasing, $k_{0}^{j}=0$ and $\int_{0}^{t} x_{s}^{j} d k_{s}^{j}=0$ for $j=1, \ldots, d, t \in \mathbb{R}_{+}$.
REMARK 2.1 ([3], Theorem 1).

1. For every $y \in \mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ with $y_{0} \in \mathbb{R}_{+}^{d}$ there exists a unique solution $\left(x_{t}, k_{t}\right)$ of the Skorokhod problem.
2. If additionally $\|Q\|<1$, then $k_{t}$ satisfies the equation

$$
\begin{equation*}
k_{t}=F(k)_{t} \tag{2.2}
\end{equation*}
$$

where

$$
F(u)_{t}=\sup _{s \leqslant t}\left[Q^{T} u_{s}-y_{s}\right]^{+}
$$

In this paper, like in [9] and [3], we make a technical assumption that

$$
\begin{equation*}
\|Q\|<1 \tag{2.3}
\end{equation*}
$$

## 3. FAST APPROXIMATION SCHEME

Let $(x, k)$ be a solution to the Skorokhod problem for $y \in \mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ with $y_{0} \in \mathbb{R}_{+}^{d}$.

For every $n \in \mathbb{N}$ we define the approximations $\left(x^{n}, k^{n}\right)$ of $(x, k)$ :

$$
\left\{\begin{align*}
k_{0}^{n} & =0, \quad x_{0}^{n}=y_{0},  \tag{3.1}\\
k_{(i+1) / n}^{n} & =\left[Q^{T} k_{i / n}^{n}-y_{(i+1) / n}\right]^{+} \vee k_{i / n}^{n}, \\
x_{(i+1) / n}^{n} & =y_{(i+1) / n}+\left(I-Q^{T}\right) k_{(i+1) / n}^{n}, \\
k_{t}^{n} & =k_{i / n}^{n}, \quad x_{t}^{n}=x_{i / n}^{n} \text { for } t \in[i / n,(i+1) / n) .
\end{align*}\right.
$$

Remark 3.1. We can write another but equivalent form of $k^{n}, x^{n}$. Note that for every $n \in \mathbb{N}, i \in \mathbb{N} \cup\{0\}$ :

$$
\begin{align*}
k_{(i+1) / n}^{n} & =\left[\left(Q^{T}-I\right) k_{i}^{n}-y_{(i+1) / n}\right]^{+}+k_{i / n}^{n}  \tag{3.2}\\
& =\left[-\left(x_{i / n}^{n}+\Delta y_{(i+1) / n)}\right]^{+}+k_{i / n}^{n},\right. \\
x_{(i+1) / n}^{n} & =x_{i / n}^{n}+\Delta y_{(i+1) / n}+\left(I-Q^{T}\right)\left[-x_{i / n}^{n}-\Delta y_{(i+1) / n}\right]^{+}, \tag{3.3}
\end{align*}
$$

where $\Delta y_{(i+1) / n}=y_{(i+1) / n}-y_{i / n}$.
Formulas (3.1) and (3.3) are equivalent, but (3.3) looks better and is simpler to calculate. The form (3.3) can be used in computer simulations.

Remark 3.2. We can see that $k_{t}^{n}$ satisfies the equations

$$
\begin{equation*}
k_{t}^{n}=F^{n}\left(k^{n,(n-)}\right)_{t}, \tag{3.4}
\end{equation*}
$$

where $F^{n}(u)_{t}=\sup _{s \leqslant t}\left[Q^{T} u_{s}-y_{s}^{(n)}\right]^{+}, u_{t}^{(n-)}=u_{(i-1) / n}, t \in[i / n,(i+1) / n)$.
The next two theorems describe some properties of scheme (3.1). In Theorem 3.1 we estimate a "distance" between a function $x$ and its approximation $x^{n}$ (and $k$ and $k^{n}$ ), and in Theorem 3.2 we prove the Lipschitz property for our scheme.

THEOREM 3.1. There exists a constant $\mathcal{C}>0$ depending only on $Q$ such that for every $y \in \mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ with $y_{0} \in \mathbb{R}_{+}^{d}, t \in \mathbb{R}_{+}$:

$$
\begin{equation*}
\sup _{s \leqslant t}\left|x_{s}^{n}-x_{s}\right|+\sup _{s \leqslant t}\left|k_{s}^{n}-k_{s}\right| \leqslant \mathcal{C} \omega_{1 / n}(y,[0, t]) . \tag{3.5}
\end{equation*}
$$

Proof. Since $\sup _{s \leqslant t}\left|x_{s}^{n}-x_{s}\right|<\|Q\| \sup _{s \leqslant t}\left|k_{s}^{n}-k_{s}\right|+\omega_{1 / n}(y,[0, t])$, we estimate only the first term, i.e. $\sup _{s \leqslant t}\left|k_{s}^{n}-k_{s}\right|$.

We assume that (2.3) is satisfied, i.e. $\|Q\|<1$.

From Remarks 2.1 and 3.2 we obtain

$$
\begin{aligned}
\sup _{s \leqslant t}\left|k_{s}^{n}-k_{s}\right|= & \sup _{s \leqslant t}\left|F^{n}\left(k^{n,(n-)}\right)_{s}-F(k)_{s}\right| \\
& \leqslant \sup _{s \leqslant t}\left|F^{n}\left(k^{n,(n-)}\right)_{s}-F^{n}\left(k^{n}\right)_{s}\right|+\sup _{s \leqslant t}\left|F^{n}\left(k^{n}\right)_{s}-F\left(k^{n}\right)_{s}\right| \\
& +\sup _{s \leqslant t}\left|F\left(k^{n}\right)_{s}-F(k)_{s}\right| \\
= & I_{t}^{1}+I_{t}^{2}+I_{t}^{3} .
\end{aligned}
$$

Now we estimate every part separately:

$$
\begin{aligned}
I_{t}^{1} & =\sup _{s \leqslant t}\left|F^{n}\left(k^{n,(n-)}\right)_{s}-F^{n}\left(k^{n}\right)_{s}\right| \leqslant\|Q\| \max _{i / n \leqslant t}\left|k_{(i-1) / n}^{n}-k_{i / n}^{n}\right| \\
& \leqslant\|Q\|^{2} \max _{i / n \leqslant t}\left|k_{(i-2) / n}^{n}-k_{(i-1) / n}^{n}\right|+\|Q\| \max _{i / n \leqslant t}\left|y_{(i-1) / n}-y_{i / n}\right| \\
& \leqslant \frac{\|Q\|}{1-\|Q\|} \omega_{1 / n}(y,[0, t]), \\
I_{t}^{2} & =\sup _{s \leqslant t}\left|F^{n}\left(k^{n}\right)_{s}-F\left(k^{n}\right)_{s}\right| \\
& \leqslant \sup _{s \leqslant t}\left|\left[Q^{T} k_{s}^{n}-y_{s}^{(n)}\right]^{+}-\left[Q^{T} k_{s}^{n}-y_{s}\right]^{+}\right| \\
& \leqslant \sup _{s \leqslant t}\left|y_{s}^{(n)}-y_{s}\right|=\omega_{1 / n}(y,[0, t]), \\
I_{t}^{3} & =\sup _{s \leqslant t}\left|F\left(k^{n}\right)_{s}-F(k)_{s}\right| \leqslant\|Q\| \sup _{s \leqslant t}\left|k_{s}^{n}-k_{s}\right| .
\end{aligned}
$$

Consequently, we have

$$
\sup _{s \leqslant t}\left|k_{s}^{n}-k_{s}\right| \leqslant \frac{\|Q\|}{1-\|Q\|} \omega_{1 / n}(y,[0, t])+\omega_{1 / n}(y,[0, t])+\|Q\| \sup _{s \leqslant t}\left|k_{s}^{n}-k_{s}\right| .
$$

So we can calculate the value of the constant $\mathcal{C}$ as follows:

$$
\sup _{s \leqslant t}\left|k_{s}^{n}-k_{s}\right| \leqslant \frac{1}{(1-\|Q\|)^{2}} \omega_{1 / n}(y,[0, t])
$$

Corollary 3.1. For every $y \in \mathbb{C}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ with $y_{0} \in \mathbb{R}_{+}^{d}$ we have

$$
\sup _{s \leqslant t}\left|x_{s}^{n}-x_{s}\right|+\sup _{s \leqslant t}\left|k_{s}^{n}-k_{s}\right| \rightarrow 0 .
$$

Theorem 3.2. There exists a constant $\mathcal{C}>0$ depending only on $Q$ such that for every $y^{1}, y^{2} \in \mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right), y_{0}^{1}, y_{0}^{2} \in \mathbb{R}_{+}^{d}$ :

$$
\sup _{s \leqslant t}\left|k_{s}^{1, n}-k_{s}^{2, n}\right|+\sup _{s \leqslant t}\left|x_{s}^{1, n}-x_{s}^{2, n}\right| \leqslant \mathcal{C} \sup _{s \leqslant t}\left|y_{s}^{1}-y_{s}^{2}\right| .
$$

Proof. As in Theorem 3.1 we need only to prove the first of the examined terms. The second can be obtained from (3.1):

$$
\begin{aligned}
\sup _{s \leqslant t}\left|k_{s}^{1, n}-k_{s}^{2, n}\right| & =\sup _{s \leqslant t}\left|F^{n}\left(k^{1, n,(n-)}\right)_{s}-F^{n}\left(k^{2, n,(n-)}\right)_{s}\right| \\
& =\sup _{s \leqslant t}\left|\left[Q^{T} k_{s}^{1, n,(n-)}-y_{s}^{1,(n)}\right]^{+}-\left[Q^{T} k_{s}^{2, n,(n-)}-y_{s}^{2,(n)}\right]^{+}\right| \\
& \leqslant\|Q\| \max _{i / n \leqslant t}\left|k_{(i-1) / n}^{1, n}-k_{(i-1) / n}^{2, n}\right|+\max _{i / n \leqslant t}\left|y_{i / n}^{1}-y_{i / n}^{2}\right| \\
& \leqslant\|Q\| \sup _{s \leqslant t}\left|k_{s}^{1, n}-k_{s}^{2, n}\right|+\sup _{s \leqslant t}\left|y_{s}^{1}-y_{s}^{2}\right|
\end{aligned}
$$

and

$$
\sup _{s \leqslant t}\left|k_{s}^{1, n}-k_{s}^{2, n}\right| \leqslant \frac{1}{1-\|Q\|} \sup _{s \leqslant t}\left|y_{s}^{1}-y_{s}^{2}\right|
$$

We obtain an easy corollary:
Corollary 3.2. There exists a constant $\mathcal{C}>0$ such that for every $y \in$ $\mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ with $y_{0} \in \mathbb{R}_{+}^{d}:$

$$
k_{t}^{n} \leqslant \mathcal{C} \sup _{s \leqslant t}\left|y_{s}\right|<+\infty
$$

From previous theorems we can obtain convergence for continuous functions. For a càdlàg function, we expect some problems with convergence in points of discontinuity.

Lemma 3.1. Assume that $y \in \mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ with $y_{0} \in \mathbb{R}_{+}^{d}$ has the form

$$
\begin{equation*}
y_{t}=\sum_{i=0}^{+\infty} y_{t_{i}} \mathbf{1}_{\left[t_{i}, t_{i+1}\right)}(t) \tag{3.6}
\end{equation*}
$$

where $0=t_{0}<t_{1}<\ldots$ Then

$$
\begin{equation*}
x_{t}^{n} \rightarrow x_{t} \quad \text { as } n \rightarrow \infty \tag{3.7}
\end{equation*}
$$

for $t \neq t_{i}, i \in \mathbb{N}$, where $\left(x_{t}, k_{t}\right)$ is a solution of the Skorokhod problem for $y_{t}$.
Proof. We prove the lemma by induction. It is well known that if $y$ is of the form (3.6), then

$$
x_{t}= \begin{cases}y_{0}, & t \in\left[0, t_{1}\right) \\ \Pi_{Q}\left(x_{t_{i-1}}+\Delta y_{t_{i}}\right), & t \in\left[t_{i}, t_{i+1}\right), i \in \mathbb{N}\end{cases}
$$

1. For $t \in\left[0, t_{1}\right)$ the assertion is satisfied by definition.
2. By (3.3) we have:

$$
x_{(i+1) / n}^{n}=\left\{\begin{array}{r}
x_{i / n}^{n}+\Delta y_{(i+1) / n}+\left(I-Q^{T}\right)\left[-x_{i / n}^{n}-\Delta y_{(i+1) / n}\right]^{+} \\
\quad \text { for } i \text { such that } i / n \leqslant t_{i}<(i+1) / n \\
x_{i / n}^{n}+\left(I-Q^{T}\right)\left[-x_{i / n}^{n}\right]^{+} \quad \text { for } i \text { such that } t_{i}<i / n<t_{i+1}
\end{array}\right.
$$

The second part, the sequence $x_{i / n}$ between jumps looks like $z_{i}$ (by (6.2) in the Appendix) for a starting point $z_{0}=\left(x_{t_{i}}+\Delta y_{t_{i}}\right)$.

Now, from Corollary 6.1 we have

$$
\lim _{n \rightarrow+\infty} x_{t}^{n}=\Pi_{Q}\left(x_{t_{i}}+\Delta y_{t_{i}}\right) \quad \text { for } t \in\left(t_{i}, t_{i+1}\right)
$$

In the next example we show that (3.7) cannot be straightened to the convergence in the Skorokhod topology $J_{1}$.

Example 3.1. Let $d=2$,

$$
Q=\left\{\begin{array}{ll}
0 & \frac{1}{2} \\
\frac{1}{2} & 0
\end{array}\right\} \quad \text { and } \quad y_{t}= \begin{cases}(0,0)^{T}, & t<1 \\
(-1,-1)^{T}, & t \geqslant 1\end{cases}
$$

The following functions are the solution of the Skorokhod problem:

$$
x_{t}=(0,0)^{T}, t \in \mathbb{R}_{+}, \quad \text { and } \quad k_{t}=\left\{\begin{array}{l}
(0,0)^{T}, t<1 \\
(2,2)^{T}, t \geqslant 1
\end{array}\right.
$$

Now, we use scheme (3.1) for these functions and try to find the limit of $\left(x^{n}, k^{n}\right)$ when $n$ tends to infinity. Then we obtain

$$
k_{t}^{n}= \begin{cases}(0,0)^{T}, & t<1 \\ (1,1)^{T}, & t \in[1,1+1 / n) \\ \left(2-1 / 2^{i}, 2-1 / 2^{i}\right)^{T}, & t \in[1+i / n, 1+(i+1) / n), \quad i \in \mathbb{N}\end{cases}
$$

and

$$
x_{t}^{n}= \begin{cases}(0,0)^{T}, & t<1, \\ \left(-\frac{1}{2},-\frac{1}{2}\right)^{T}, & t \in[1,1+1 / n) \\ \left(-1 / 2^{i+1},-1 / 2^{i+1}\right)^{T}, & t \in[1+i / n, 1+(i+1) / n), \quad i \in \mathbb{N}\end{cases}
$$

Since $\sup _{t \leqslant 2}\left|x_{t}^{n}\right|=\frac{1}{2}$, we have the solution $x^{n} \nrightarrow x$ in $J_{1}$.
Using the notation of jump point, we can obtain another type of problems. For example, for jump at $t_{1}=\frac{1}{3}$ the limit $\lim _{n \rightarrow+\infty} x_{t_{1}}^{n}$ does not exist.

Classical topology $J_{1}$ is too strong in order to obtain convergence for our scheme. There exists a topology $S$ that is weaker than $J_{1}$, which is obviously weaker than the uniform topology. The $S$ topology has been introduced by Jakubowski in [11] and in the next papers (e.g. [12]) good criteria of convergence in topology $S$ were given. From the point of view of computer simulation and numerical methods convergence in the $S$ topology is sufficient.

From Lemma 2.14 in [11] we obtain
COROLLARY 3.3. If y satisfies the assumption of Lemma 3.1, then

$$
\begin{equation*}
\left(x^{n}, k^{n}\right) \rightarrow(x, k) \text { in }\left(\mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{2 d}\right), S\right) \tag{3.8}
\end{equation*}
$$

The following theorem can be generalized for càdlàg functions.
THEOREM 3.3. If $y \in \mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ and $y_{0} \in \mathbb{R}_{+}^{d}$, then

$$
\begin{equation*}
\left(x^{n}, k^{n}\right) \rightarrow(x, k) \text { in }\left(\mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{2 d}\right), S\right) \tag{3.9}
\end{equation*}
$$

Proof. For all $y \in \mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ and all $\epsilon>0$ there exists $y^{\epsilon} \in \mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ satisfying the assumption of Lemma 3.1 so that $\sup _{s \leqslant t}\left|y_{s}^{\epsilon}-y_{s}\right| \leqslant \epsilon$.

Let $t_{0}=0$ and

$$
t_{i+1}=\inf \left\{s>t_{i}:\left|y_{s}-y_{t_{i}}\right| \geqslant \epsilon\right\} .
$$

Then

$$
y_{t}^{\epsilon}=y_{t_{i}}, \quad t \in\left[t_{i}, t_{i+1}\right)
$$

Let the pair $\left(x^{\epsilon}, k^{\epsilon}\right)$ be a solution of the Skorokhod problem for $y^{\epsilon}$. Then from Lemma 3.1 we get

$$
\left(x^{\epsilon, n}, k^{\epsilon, n}\right) \rightarrow\left(x^{\epsilon}, k^{\epsilon}\right) \text { in }\left(\mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{2 d}\right), S\right)
$$

To prove the assertion we need to show that

$$
\lim _{\epsilon \rightarrow 0} \sup _{n} \sup _{s \leqslant t}\left|k_{s}^{\epsilon, n}-k_{s}^{n}\right|=0
$$

From Theorem 3.2 we have

$$
\sup _{s \leqslant t}\left|k_{s}^{\epsilon, n}-k_{s}^{n}\right| \leqslant \mathcal{C} \sup _{s \leqslant t}\left|y_{s}^{\epsilon(n)}-y_{s}^{(n)}\right| \leqslant \mathcal{C} \epsilon
$$

REMARK 3.3. If $y \in \mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{d}\right)$ and $y_{0} \in \mathbb{R}_{+}^{d}$, then $x^{n} \rightarrow x$ for continuity point of $y$ and $\left\{x^{n}\right\}$ is relatively $S$-compact.

## 4. FAST APPROXIMATION SCHEME FOR SDE

Let $Z$ be an $\left(\mathcal{F}_{t}\right)$-adapted semimartingale. Let us recall that the pair $(X, K)$ of $\left(\mathcal{F}_{t}\right)$-adapted processes is said to be a strong solution of $(1.1)$ if $(X, K)$ is a solution to the Skorokhod problem associated with the semimartingale

$$
\begin{equation*}
Y_{t}=X_{0}+\int_{0}^{t} \sigma\left(X_{s-}\right) d Z_{s}, \quad t \in \mathbb{R}_{+} \tag{4.1}
\end{equation*}
$$

REMARK 4.1. If $\sigma$ is Lipschitz continuous, then there exists a unique strong solution to the SDE (1.1).

Using formulas (3.1) we can define a "fast" scheme for SDE:

$$
\begin{aligned}
X_{0}^{n} & =X_{0}, \quad K_{0}^{n}=0, \\
K_{(i+1) / n}^{n} & =\left[Q^{T} K_{i / n}^{n}-\left(X_{i / n}^{n}+\sigma\left(X_{i / n}^{n}\right)\left(Z_{(i+1) / n}-Z_{i / n}\right)\right)\right]^{+} \vee K_{i / n}^{n}, \\
X_{(i+1) / n}^{n} & =X_{i / n}^{n}+\sigma\left(X_{i / n}^{n}\right)\left(Z_{(i+1) / n}-Z_{i / n}\right)+\left(1-Q^{T}\right) K_{(i+1) / n}^{n}, \\
\left(X_{t}^{n}, K_{t}^{n}\right) & =\left(X_{i / n}^{n}, K_{i / n}^{n}\right), \quad t \in[i / n,(i+1) / n) .
\end{aligned}
$$

Lemma 4.1. Assume that there exist stoping times $\left\{\tau_{i}\right\} \subset \mathbb{R}_{+}$such that $0=$ $\tau_{0}<\tau_{1}<\ldots$ and $\left\{Z_{i}\right\} \subset \mathbb{R}^{d}$. If $Z$ is a semimartingale such that $Z_{t}=Z_{i}$ for $t \in\left[\tau_{i}, \tau_{i+1}\right), i \in \mathbb{N} \cup\{0\}$, then

$$
\begin{equation*}
X_{t}^{n} \rightarrow X_{t} \quad \text { for } t \neq t_{i} \tag{4.2}
\end{equation*}
$$

Proof. We define

$$
X_{t}= \begin{cases}X_{0}, & t \in\left[0, \tau_{1}\right) \\ \Pi_{Q}\left(X_{\tau_{i-1}}+\sigma\left(X_{\tau_{i-1}}\right) \Delta Z_{\tau_{i}}\right), & t \in\left[\tau_{i}, \tau_{i+1}\right), i \in \mathbb{N}\end{cases}
$$

The rest of the proof is the same as for Lemma 3.1. We need only to change $\Delta y_{(i+1) / n}^{(n)}$ by $\sigma\left(X_{\tau_{i-1}}\right) \Delta Z_{\tau_{i}}$.

Theorem 4.1. Assume that $\sigma$ is Lipschitz continuous. Then

$$
\begin{equation*}
\left(X^{n}, K^{n}\right) \underset{\mathcal{P}}{ }(X, K) \text { in }\left(\mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{2 d}\right), S\right) \tag{4.3}
\end{equation*}
$$

Proof. As in Theorem 3.3, for all $\epsilon>0$ we construct a "piecewise constant" martingale $Z^{\epsilon}$. It follows that for all $\epsilon>0$ there exists $Z^{\epsilon}$ such that

$$
\sup _{s \leqslant t}\left|Z_{s}-Z_{s}^{\epsilon}\right| \leqslant \epsilon
$$

Let the pair $\left(X^{\epsilon n}, K^{\epsilon n}\right)$ be a solution of the Skorokhod problem for the semimartingale

$$
Y_{t}=X_{0}+\int_{0}^{t} \sigma\left(X_{s-}\right) d Z_{s}^{\epsilon}, \quad t \in \mathbb{R}_{+} .
$$

From Lemma 4.1 we have the convergence

$$
\left(X^{\epsilon n}, K^{\epsilon n}\right) \rightarrow\left(X^{\epsilon}, K^{\epsilon}\right) \text { in }\left(\mathbb{D}\left(\mathbb{R}_{+}, \mathbb{R}^{2 d}\right), S\right)
$$

To complete the proof we need to show that, for all $\eta>0$,

$$
\lim _{\epsilon \rightarrow 0} \limsup _{n} P\left(\sup _{s \leqslant t}\left|X_{s}^{\epsilon n}-X_{s}^{n}\right|>\eta\right)=0
$$

Using Theorem 3.2, we obtain

$$
\begin{aligned}
\sup _{s \leqslant t}\left|X_{s}^{\epsilon n}-X_{s}^{n}\right| \leqslant & \mathcal{C} \sup _{s \leqslant t}\left|Y_{s}^{\epsilon n}-Y_{s}^{n}\right| \\
= & \mathcal{C} \sup _{s \leqslant t}\left|\int_{0}^{s} \sigma\left(X_{u-}^{n}\right) d Z_{u}^{(n)}-\int_{0}^{s} \sigma\left(X_{u-}^{\epsilon n}\right) d Z_{u}^{\epsilon,(n)}\right| \\
\leqslant & \mathcal{C} \sup _{s \leqslant t}\left|\int_{0}^{s} \sigma\left(X_{u-}^{n}\right) d Z_{u}^{(n)}-\int_{0}^{s} \sigma\left(X_{u-}^{\epsilon n}\right) d Z_{u}^{(n)}\right| \\
& +\mathcal{C} \sup _{s \leqslant t}\left|\int_{0}^{s} \sigma\left(X_{u-}^{\epsilon n}\right) d Z_{u}^{(n)}-\int_{0}^{s} \sigma\left(X_{u-}^{\epsilon n}\right) d Z_{u}^{\epsilon,(n)}\right| \\
= & \mathcal{C} \sup _{s \leqslant t}\left|\int_{0}^{s}\left(\sigma\left(X_{u-}^{n}\right)-\sigma\left(X_{u-}^{\epsilon n}\right)\right) d Z_{u}^{(n)}\right|+\mathcal{C} \sup _{s \leqslant t}\left|H_{s}^{\epsilon, n}\right|, \\
H_{t}^{\epsilon, n}= & \int_{0}^{t} \sigma\left(X_{s-}^{\epsilon n}\right) d Z_{s}^{(n)}-\int_{0}^{t} \sigma\left(X_{s-}^{\epsilon n}\right) d Z_{s}^{\epsilon,(n)} \\
= & \int_{0}^{t} \sigma\left(X_{s-}^{\epsilon n}\right) d\left(Z_{s}^{(n)}-Z_{s}^{\epsilon,(n)}\right) \\
= & \sigma\left(X_{t}^{\epsilon n}\right)\left(Z_{t}^{(n)}-Z_{t}^{\epsilon,(n)}\right)-\int_{0}^{t}\left(Z_{s-}^{(n)}-Z_{s-}^{\epsilon,(n)}\right) d \sigma\left(X_{s}^{\epsilon n}\right) \\
& -\left[\sigma\left(X_{t}^{\epsilon n}\right),\left(Z_{t}^{(n)}-Z_{t}^{\epsilon,(n)}\right)\right] .
\end{aligned}
$$

Obviously,

$$
\left[\sigma\left(X_{t}^{\epsilon n}\right),\left(Z_{t}^{(n)}-Z_{t}^{\epsilon,(n)}\right)\right] \leqslant\left(\left[\sigma\left(X_{t}^{\epsilon n}\right)\right]\right)^{1 / 2}\left(\left[\left(Z_{t}^{(n)}-Z_{t}^{\epsilon,(n)}\right)\right]\right)^{1 / 2}
$$

By definition, $X_{t}^{\epsilon n}$ has the form

$$
X_{t}^{\epsilon n}=X_{0}+\int_{0}^{t} \sigma\left(X^{\epsilon_{s-}^{n}}\right) d Z_{s}^{\epsilon, n}+\left(1-Q^{T}\right) K_{t}^{\epsilon n}
$$

So, we can write the inequalities

$$
\begin{aligned}
\sup _{s \leqslant t}\left|X_{t}^{\epsilon n}\right| & \leqslant\left|X_{0}\right|+\sup _{s \leqslant t}\left|\int_{0}^{t} \sigma\left(X^{\epsilon_{u-} n}\right) d Z_{u}^{\epsilon, n}\right|+\left(1-Q^{T}\right) \sup _{s \leqslant t}\left|K^{\epsilon_{s}^{n}}\right| \\
& \leqslant\left|X_{0}\right|+2 \mathcal{C} \sup _{s \leqslant t}\left|\int_{0}^{t} \sigma\left(X^{\epsilon_{u-}^{n}}\right) d Z_{u}^{\epsilon, n}\right|
\end{aligned}
$$

From Gronwall's lemma it follows that $\left\{\sup \left|X^{\epsilon^{n}}\right|\right\}$ is bounded for $\sigma$ satisfying the Lipschitz condition. So, if $\left\{\sigma\left(\left|X^{\epsilon^{n}}\right|\right)\right\}$ is bounded in probability, then

$$
\int_{0}^{t} \sigma\left(X^{\epsilon_{s-}}\right) d Z_{s}^{\epsilon, n}
$$

satisfies $U T$ condition.
Because $\left\{K^{\epsilon^{n}}\right\}$ is bounded in probability, this means that it also satisfies $U T$. $\left\{X^{\epsilon^{n}}\right\}$ satisfies $U T$ as a sum of two processes that satisfy $U T$. So, $\sigma\left(X^{\epsilon^{n}}\right)$ satisfies $U T$ for $\sigma \in C^{2}$.

## 5. FAST APPROXIMATION SCHEME FOR DIFFUSION

Consider SDE with reflection on $\mathbb{R}_{+}^{d}$ of the form

$$
\begin{equation*}
X_{t}=X_{0}+\int_{0}^{t} b\left(X_{s}\right) d s+\int_{0}^{t} \sigma\left(X_{s}\right) d W_{s}+\left(1-Q^{T}\right) K_{t} \tag{5.1}
\end{equation*}
$$

where $W$ is a $d$-dimensional Wiener process, and $b: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}, \sigma: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d} \otimes \mathbb{R}^{d}$.
REMARK 5.1. If $b$ and $\sigma$ are Lipschitz continuous, then there exists a unique strong solution of the SDE (5.1).

Let us define

$$
\begin{aligned}
X_{0}^{n}= & X_{0}, \quad K_{0}^{n}=0 \\
K_{(i+1) / n}^{n}= & {\left[Q^{T} K_{i / n}^{n}-\left(X_{i / n}^{n}+b\left(X_{i / n}^{n}\right) n^{-1}+\sigma\left(X_{i / n}^{n}\right)\left(W_{(i+1) / n}-W_{i / n}\right)\right)\right]^{+} } \\
& \vee K_{i / n}^{n} \\
X_{(i+1) / n}^{n}= & X_{i / n}^{n}+b\left(X_{i / n}^{n}\right) n^{-1}+\sigma\left(X_{i / n}^{n}\right)\left(W_{(i+1) / n}-W_{i / n}\right) \\
& +\left(1-Q^{T}\right) K_{(i+1) / n}^{n}, \\
\left(X_{t}^{n}, K_{t}^{n}\right)= & \left(X_{i / n}^{n}, K_{i / n}^{n}\right), \quad t \in[i / n,(i+1) / n) .
\end{aligned}
$$

We can see that $X^{n}$ satisfies the equation

$$
\begin{equation*}
X_{t}^{n}=X_{0}^{n}+\int_{0}^{t} b\left(X_{s-}^{n}\right) d \rho_{s}^{n}+\int_{0}^{t} \sigma\left(X_{s-}^{n}\right) d W_{s}^{(n)}+\left(1-Q^{T}\right) K_{t}^{n} \tag{5.2}
\end{equation*}
$$

THEOREM 5.1. Let the assumptions of Remark 5.1 be satisfied and let $(X, K)$ be a strong solution to the $\operatorname{SDE}$ (5.1). Then for every $p \in \mathbb{N}$

$$
\begin{equation*}
E \sup _{s \leqslant t}\left|X_{s}^{n}-X_{s}\right|^{2 p}=\mathcal{O}\left(\left(\frac{\ln n}{n}\right)^{p}\right) \tag{5.3}
\end{equation*}
$$

First we prove the following lemma:
LEMMA 5.1. Under the assumptions as in Theorem 5.1 we obtain

$$
\begin{equation*}
\sup _{n} E \sup _{s \leqslant t}\left|X_{s}^{n}\right|^{2 p}<+\infty \tag{5.4}
\end{equation*}
$$

Proof. We have

$$
\begin{equation*}
\sup _{s \leqslant t}\left|X_{s}^{n}-X_{0}^{n}\right| \leqslant \mathcal{C} \sup _{s \leqslant t}\left|\int_{0}^{s} \sigma\left(X_{u-}^{n}\right) d W_{u}^{(n)}+\int_{0}^{s} b\left(X_{u-}^{n}\right) d \rho_{u}^{n}\right|, \tag{5.5}
\end{equation*}
$$

which implies

$$
\sup _{s \leqslant t}\left|X_{s}^{n}-X_{0}^{n}\right|^{2 p} \leqslant 2 \mathcal{C} \sup _{s \leqslant t}\left|\int_{0}^{s} \sigma\left(X_{u-}^{n}\right) d W_{u}^{(n)}\right|^{2 p}+2 \mathcal{C} \sup _{s \leqslant t}\left|\int_{0}^{s} b\left(X_{u-}^{n}\right) d \rho_{u}^{n}\right|^{2 p}
$$

Now, because $b$ and $\sigma$ are Lipschitz, we have

$$
\begin{aligned}
E \sup _{s \leqslant t}\left|X_{s}^{n}-X_{0}^{n}\right|^{2 p} & \leqslant 2 \mathcal{C} E\left(\int_{0}^{t} \sigma\left(X_{s-}^{n}\right) d W_{s}^{(n)}\right)^{2 p}+2 \mathcal{C} E\left(\int_{0}^{t}\left|b\left(X_{s}^{n}\right)\right| d s\right)^{2 p} \\
& \leqslant 2 \mathcal{C} E \int_{0}^{t} \sigma^{2 p}\left(X_{s-}^{n}\right) d \rho_{s}^{n}+2 \mathcal{C} E \int_{0}^{t} b^{2 p}\left(X_{s^{-}}^{n}\right) d \rho_{s}^{n} \\
& \leqslant \mathcal{C} E \int_{0}^{t}\left(\left(X_{s-}^{n}\right)^{2 p}+1\right) d \rho_{s}^{n} \\
& \leqslant \mathcal{C}\left(1+\int_{0}^{t} E \sup _{u \leqslant s}\left|X_{u}^{n}-X_{0}^{n}\right|^{2 p} d s\right) .
\end{aligned}
$$

Thus, from Gronwall's lemma we have the assertion.
Proof of Theorem 5.1. By definition we have

$$
\begin{aligned}
X_{t}^{n}-X_{t}= & \int_{0}^{t}\left(\sigma\left(X_{s-}^{n}\right)-\sigma\left(X_{s-}\right)\right) d W_{s}^{(n)} \\
& +\int_{0}^{t}\left(b\left(X_{s-}^{n}\right)-b\left(X_{s-}\right)\right) d \rho_{s}^{n}+\left(1-Q^{T}\right)\left(K_{t}^{n}-K_{t}\right)
\end{aligned}
$$

Because $b$ and $\sigma$ are Lipschitz, we get

$$
E \sup _{s \leqslant t}\left|X_{s}^{n}-X_{s}\right|^{2 p} \leqslant 2 \mathcal{C}\left(E \sup _{s \leqslant t}\left|K_{s}^{n}-K_{s}\right|^{2 p}+\int_{0}^{t} E \sup _{u \leqslant s}\left|X_{u}^{n}-X_{u}\right|^{2 p} d s\right)
$$

From Gronwall's lemma we obtain

$$
E \sup _{s \leqslant t}\left|X_{s}^{n}-X_{s}\right|^{2 p} \leqslant 2 \mathcal{C} E \sup _{s \leqslant t}\left|K_{s}^{n}-K_{s}\right|^{2 p}
$$

In the same way we can prove that

$$
E \sup _{s \leqslant t}\left|X_{s}^{n}\right|^{2} \leqslant \mathcal{C} E \sup _{s \leqslant t}\left|K_{s}^{n}\right|^{2}
$$

Since

$$
K_{t}^{n}=\sup _{s \leqslant t}\left[Q^{T} K^{n,(n-)}-\left(X_{0}^{n}+\int_{0}^{s} b\left(X_{u-}^{n}\right) d \rho_{u}^{n}+\int_{0}^{s} \sigma\left(X_{u-}^{n}\right) d W_{u}^{(n)}\right)\right]^{+}
$$

and

$$
K_{t}=\sup _{s \leqslant t}\left[Q^{T} K_{s}-\left(X_{0}^{n}+\int_{0}^{s} b\left(X_{u-}\right) d \rho_{u}+\int_{0}^{s} \sigma\left(X_{u-}\right) d W_{u}\right)\right]^{+}
$$

we have

$$
\begin{aligned}
K_{t}^{n}-K_{t}= & \sup _{s \leqslant t}\left[Q^{T} K_{s}^{n,(n-)}-\left(X_{0}^{n}+\int_{0}^{s} b\left(X_{u-}^{n}\right) d \rho_{u}^{n}+\int_{0}^{s} \sigma\left(X_{u-}^{n}\right) d W_{u}^{(n)}\right)\right]^{+} \\
& -\sup _{s \leqslant t}\left[Q^{T} K_{s}^{n}-\left(X_{0}^{n}+\int_{0}^{s} b\left(X_{u-}^{n}\right) d \rho_{u}^{n}+\int_{0}^{s} \sigma\left(X_{u-}^{n}\right) d W_{u}^{(n)}\right)\right]^{+} \\
& +\sup _{s \leqslant t}\left[Q^{T} K_{s}^{n}-\left(X_{0}^{n}+\int_{0}^{s} b\left(X_{u-}^{n}\right) d \rho_{u}^{n}+\int_{0}^{s} \sigma\left(X_{u-}^{n}\right) d W_{u}^{(n)}\right)\right]^{+} \\
& -\sup _{s \leqslant t}\left[Q^{T} K_{s}^{n}-\left(X_{0}+\int_{0}^{s} b\left(X_{u-}\right) d \rho_{u}+\int_{0}^{s} \sigma\left(X_{u-}\right) d W_{u}\right)\right]^{+} \\
& +\sup _{s \leqslant t}\left[Q^{T} K_{s}^{n}-\left(X_{0}+\int_{0}^{s} b\left(X_{u-}\right) d \rho_{u}+\int_{0}^{s} \sigma\left(X_{u-}\right) d W_{u}\right)\right]^{+} \\
& -\sup _{s \leqslant t}\left[Q^{T} K_{s}-\left(X_{0}+\int_{0}^{s} b\left(X_{u-}\right) d \rho_{u}+\int_{0}^{s} \sigma\left(X_{u-}\right) d W_{u}\right)\right]^{+} \\
= & I_{t}^{1}+I_{t}^{2}+I_{t}^{3} .
\end{aligned}
$$

Now we estimate every part separately:

$$
\begin{aligned}
& I_{t}^{1} \leqslant \sup _{s \leqslant t}\left|K_{s}^{n,(n-)}-K_{s}^{n}\right| \leqslant \sup _{s \leqslant t}\left|\sigma\left(X_{s-}^{n}\right)\left(W_{s}-W_{s}^{(n)}\right)+b\left(X_{s-}^{n}\right)\left(s-\rho_{s}^{n}\right)\right| \\
& I_{t}^{2} \leqslant \sup _{u \leqslant s}\left|\int_{0}^{s}\left(b\left(X_{u-}^{n}\right)-b\left(X_{u-}\right)\right) d \rho_{u}^{n}+\int_{0}^{s}\left(\sigma\left(X_{u-}^{n}\right)-\sigma\left(X_{u-}\right)\right) d W_{u}^{(n)}\right| \\
& I_{t}^{3} \leqslant \sup _{s \leqslant t}\left|K_{s}^{n}-K_{s}\right|
\end{aligned}
$$

and we have

$$
\begin{aligned}
E \sup _{s \leqslant t}\left|K_{s}-K_{s}^{n}\right|^{2 p} & \leqslant \mathcal{C}\left(E \sup _{s \leqslant t}\left|W_{s}-W_{s}^{(n)}\right|^{2 p}+\int_{0}^{s} E \sup _{u \leqslant s}\left|K_{u}-K_{u}^{n}\right|^{2 p} d u\right) \\
& \leqslant \mathcal{C} E\left(\omega_{1 / n}(W,[0, t])\right)^{2 p} \\
& =\mathcal{O}\left(\left(\frac{\ln n}{n}\right)^{p}\right) .
\end{aligned}
$$

## 6. APPENDIX. $\Pi_{Q}$ PROJECTION

Finding the projection $\pi$ on the domain $D$ is the standard technique to obtain a solution of the Skorokhod problem. In [3] we define a projection on the orthant $\mathbb{R}_{+}^{d}$ as follows:

REMARK 6.1. $\Pi_{Q}: \mathbb{R}^{d} \rightarrow \mathbb{R}_{+}^{d}$ is defined by

$$
\Pi_{Q}(z)=z+\left(I-Q^{T}\right) \bar{r}
$$

where $\bar{r}$ satisfies the equation $\bar{r}=\left[Q^{T} \bar{r}-z\right]^{+}$.
In that definition, we have to find the fixed point $\bar{r}$. Typically, we use the approximation sequence of $\bar{r}$ and $\bar{z}$ :

$$
\left\{\begin{align*}
\bar{r}_{0} & =0,  \tag{6.1}\\
\bar{z}_{0} & =z, \\
\bar{r}_{n+1} & =\left[Q^{T} \bar{r}_{n}-z\right]^{+}, \quad n \in \mathbb{N} \cup\{0\}, \\
\bar{z}_{n+1} & =z+\left(I-Q^{T}\right) \bar{r}_{n+1}, \quad n \in \mathbb{N} \cup\{0\} .
\end{align*}\right.
$$

It is easy to see that

$$
\lim _{n \rightarrow+\infty} \bar{r}_{n}=\bar{r} \quad \text { and } \quad \lim _{n \rightarrow+\infty} \bar{z}_{n}=\Pi_{Q}(z)
$$

Using simple calculations, we can obtain an equivalent formula for $\bar{r}_{n+1}$ :
REMARK 6.2. We have

$$
\bar{r}_{n+1}=\left[Q^{T} \bar{r}_{n}-z\right]^{+}=\left[-\left(z+\left(I-Q^{T}\right) \bar{r}_{n}\right)+\bar{r}_{n}\right]^{+}=\left[\bar{z}_{n}+\bar{r}_{n}\right]^{+} .
$$

Now we define another sequence starting from the same point:

$$
\begin{align*}
z_{0} & =z \\
z_{n+1} & =z_{n}+\left(I-Q^{T}\right)\left[-z_{n}\right]^{+}, \quad n \in \mathbb{N} \cup\{0\} \tag{6.2}
\end{align*}
$$

That sequence looks like that in our scheme used for a constant function $y_{t}=z$ ( $\Delta y_{t}=0$ ).

Once again simple calculations lead to obtaining an equivalent formula:
REMARK 6.3. We have

$$
z_{n+1}=z_{n}+\left(I-Q^{T}\right)\left[-z_{n}\right]^{+}=z+\left(I-Q^{T}\right) \sum_{i=0}^{n}\left[-z_{i}\right]^{+}
$$

Sequences $z_{n}$ and $\bar{z}_{n}$ look different, but in fact they are only different representations of the same sequence.

Lemma 6.1. For every $z \in \mathbb{R}^{d}$ and for all $n \in \mathbb{N} \cup\{0\}$ we have

$$
\begin{equation*}
z_{n}=\bar{z}_{n} \tag{6.3}
\end{equation*}
$$

Proof. The proof will be done by induction. For $n=0$ we have

$$
z_{0}=z=\bar{z}_{0} .
$$

Now assume that $z_{i}=\bar{z}_{i}$ for $i=0, \ldots, n$. Then from (6.1) and Remark 6.2 we have

$$
\begin{equation*}
\bar{r}_{i}=\bar{r}_{i-1}+\left[-\bar{z}_{i-1}\right]^{+} \tag{6.4}
\end{equation*}
$$

for $i=0, \ldots, n$.
Now we check

$$
\begin{aligned}
\bar{z}_{n+1}-z_{n+1} & =z+\left(I-Q^{T}\right) \bar{r}_{n+1}-z_{n}+\left(I-Q^{T}\right)\left[-z_{n}\right]^{+} \\
& =\bar{z}_{n}+\left(I-Q^{T}\right)\left(\left[-\bar{z}_{n}+\bar{r}_{i}\right]^{+}-\bar{r}_{n}\right)-z_{n}+\left(I-Q^{T}\right)\left[-z_{n}\right]^{+} \\
& =\left(\bar{z}_{n}-z_{n}\right)+\left(I-Q^{T}\right)\left(\left[-\bar{z}_{n}+\bar{r}_{n}\right]^{+}-\bar{r}_{n}-\left[-z_{n}\right]^{+}\right) \\
& =\left(I-Q^{T}\right)\left(\left[-\bar{z}_{n}+\bar{r}_{n}\right]^{+}-\bar{r}_{n}-\left[-\bar{z}_{n}\right]^{+}\right) .
\end{aligned}
$$

Let us define

$$
\begin{equation*}
R_{n}^{j}=\left[-\bar{z}_{n}^{j}+\bar{r}_{n}^{j}\right]^{+}-\bar{r}_{n}^{j}-\left[-\bar{z}_{n}^{j}\right]^{+}, \quad j=1, \ldots, d \tag{6.5}
\end{equation*}
$$

It is easy to show that if $\bar{z}_{n}^{j} \leqslant 0$, then $R_{n}^{j}=0$. To complete the proof we need to check whether $R_{n}^{j}=0$ when $\bar{z}_{n}^{j}>0$.

Without loss of generality we can assume that $j=1$. Then

$$
\begin{aligned}
\bar{z}_{n}^{1} & =z_{n}^{1} \\
& =z_{n-1}^{1}+\left[-z_{n-1}^{1}\right]^{+}-q_{21}\left[-z_{n-1}^{2}\right]^{+}+\ldots-q_{d 1}\left[-z_{n-1}^{d}\right]^{+} \\
& \leqslant z_{n-1}^{1}+\left[-z_{n-1}^{1}\right]^{+} \\
& =\bar{z}_{n-1}^{1}+\left[-\bar{z}_{n-1}^{1}\right]^{+} .
\end{aligned}
$$

Consequently, if $\bar{z}_{n}^{1}>0$, then $\bar{z}_{n-1}^{1}>0$. In the same way we can prove that $\bar{z}_{i}^{1}>0$ for $i=n-1, \ldots, 0$. If $\bar{z}_{0}^{1}>0$, then $\bar{r}_{1}^{1}=0$, and by (6.4) we have $\bar{r}_{n}^{1}=0$. Thus $R_{n}^{1}=0$.

Corollary 6.1. We have

$$
\lim _{n \rightarrow+\infty} z_{n}=\Pi_{Q}(z)
$$

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Faculty of Mathematics and Computer Science
Nicholas Copernicus University
ul. Chopina 12/18
87-100 Toruń, Poland
E-mail: kczark@mat.umk.pl

